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Technical Manual

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CH-3721F

Fast Acquisition Enhanced Sensitivity 44 Channels PS2 Interface GPS Receiver

1. FEATURES

- 44 channels to acquire and track satellites simultaneously
- Industry-leading TTFF speed
- Signal detection better than -158 dBm
- SBAS (WAAS/EGNOS) capable
- Selectable User Profiles with ability to change and save configuration to Flash
- Cold start < 45sec
- Hot start < 1sec
- Accuracy 5m CEP
- RS232 signal output via 6-pin PS2 connector.
- 49.8 mm x 43.7 mm x 17.6 mm
- RoHS compliance

The **CH-3721F** is a compact all-in-one GPS receiver that continuously tracks all satellites in view and provides accurate satellite positioning data.

Its 44 parallel channels and 20000+ correlators provide fast satellite signal acquisition and short start-up time. Acquisition sensitivity of -155dBm and tracking sensitivity of -158 dBm offer good performance even under difficult environments.

The **CH-3721F** is optimized for applications requiring good performance and low cost; it is suitable for a wide range of handhelds, asset tracking, Notebook, PDA-centric personal navigation system, and vehicle navigation products.

2. SPECIFICATIONS

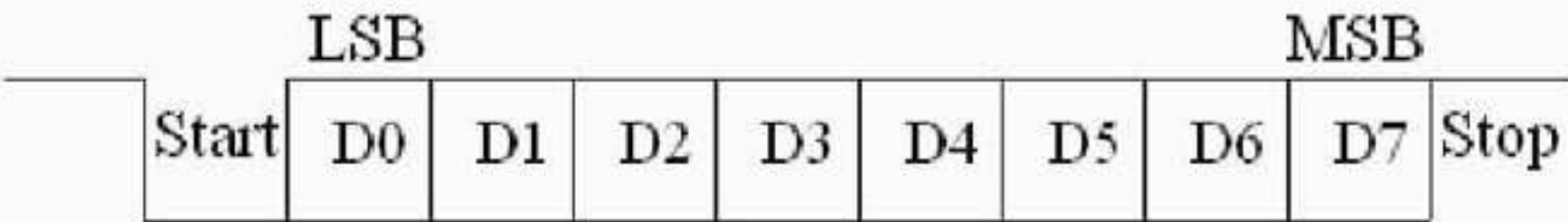
Parameter	Specification
Receiver Type	44 channels
Re-acquisition sensitivity	-155dBm
Tracking sensitivity	-158dBm
Cold start sensitivity	-137dBm
Receiver frequency	1575.42MHz
Code	C/A code
Accuracy (1) Position (2) Velocity	5m CEP 0.1m/sec
Startup Time hot start warm start cold start	< 1 sec < 35 sec < 45 sec
Signal Reacquisition	<1s
Update Rate	1Hz
Operational Limits (1) Altitude (2) velocity	< 18,000m < 500m/s
Dynamics	4G (39.2m/sec ²)
Datum	WGS-84
Protocol	NMEA-0183 V3.01
Serial Interface	RS232 signal output via PS2 connector.
Input Voltage	+3.0V to +5.5V
Power Consumption	180mW
Connector	6 pins PS2 connector with 1.8M cable

3. GPS STATUS INDICATOR

The CH-3721F provides GPS status indicator. On board LED shows fix or non-fix. In fix mode, the LED will light for 1 second and turn off for 1 second. In another mode, the pin will light for 2 seconds and turn off for 2 seconds

4. COMMUNICATION SEPECIFICATIONS

Item	Description
Interface	Full duplex serial interface
Bit rate	4800/9600/38400/115200 bps
Start bit	1bit
Stop bit	1bit
Data bit	8bit
Parity	none
Transmission data	SACII NMEA0183 Ver:3.01
Update rate	1Hz
Output sentence	GGA/GSA/GSV/RMC(typ)



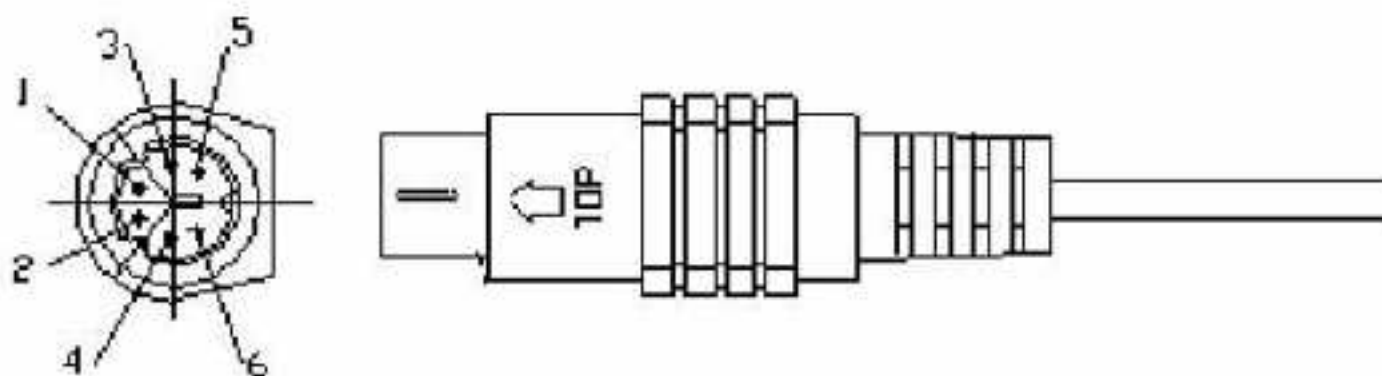
NOTE:

1. Update rate can be modified by request but the 1 Hz refresh time is the fastest.
2. Output sentences of GGA/GSA/GSV/RMC/GGL/VTG and ZDA can be selected by request. When Bit rate is below 9600bps, we suggest that to transmit other four among seven types of output sentences out from module per times should be preferred. It can avoid data delaying for navigation products.

5. ENVIRONMENT SPECIFICATION

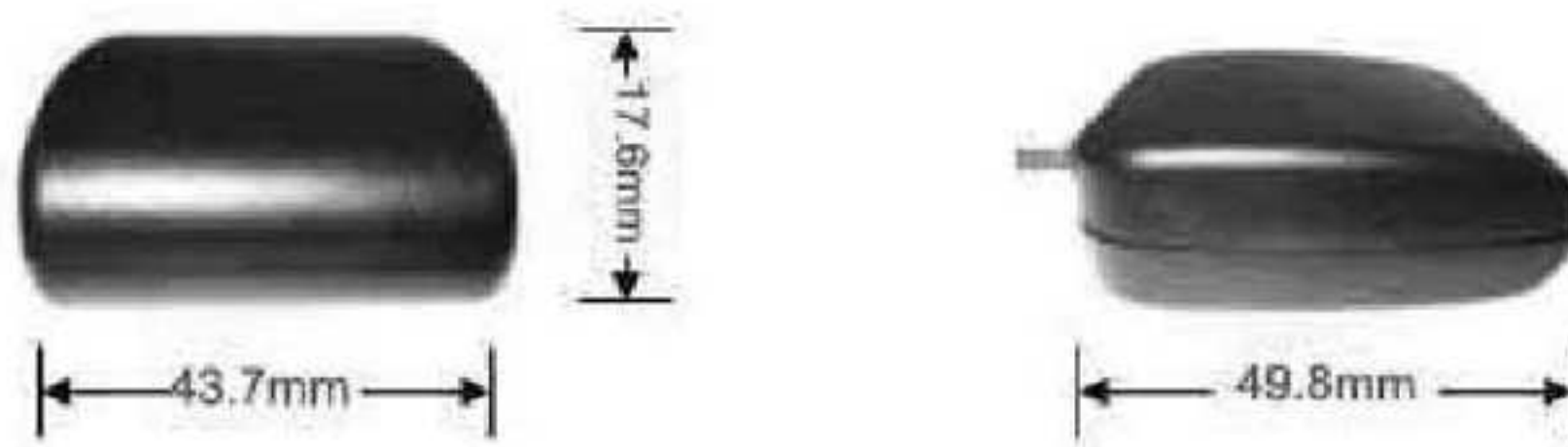
Parameter		Specification
Temperature	Operating	-20℃~+60℃
	Storage	-40℃~+80℃
Humidity		5%~95%

6. PIN ASSIGNMENT



PIN	Signal name	Description	Notes
1	GND	Ground	
2	VCC	Power input	3.0V to 5.5V
3	NC	No use	
4	RS232_RXD0	RS232 signal received data line	
5	RS232_TXD0	RS232 signal transmitted data line	
6	NC	No use	

7. MECHANIC DIMENSION



Parameter	Specification
Physical dimension	49.8mm X 43.7mm X 17.6mm
Weight	14g

8. CUSTOMIZED PACKAGE

- Color box
- CD (Including user manual and GPS test program)

9. APPROVED NMEA MESSAGE

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org

9.1 GGA – GLOBAL POSITIONING SYSTEM FIX DATA

Time, position and fix related data for a GPS receiver.

Structure:

\$GPGGA,hhmmss.sss,ddmm.mmmm,a,dddmm.mmmm,a,x,xx,x.x,x.x,M,x.x,M,x.x,xxxx*hh<CR><LF>

1 2 3 4 5 6 7 8 9 10 11 12 13

Example:

\$GPGGA,060932.448,2447.0959,N,12100.5204,E,1,08,1.1,108.7,M,,,0000*0E<CR><LF>

Field	Name	Example	Description
1	UTC Time	060932.448	UTC of position in hhmmss.sss format, (000000.00 ~ 235959.99)
2	Latitude	2447.0959	Latitude in ddmm.mmmm format Leading zeros transmitted
3	N/S Indicator	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
4	Longitude	12100.5204	Longitude in dddmm.mmmm format Leading zeros transmitted
5	E/W Indicator	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
6	GPS quality indicator	1	GPS quality indicator 0: position fix unavailable 1: valid position fix, SPS mode 2: valid position fix, differential GPS mode 3: GPS PPS Mode, fix valid 4: Real Time Kinematic. System used in RTK mode with fixed integers 5: Float RTK. Satellite system used in RTK mode. Floating integers 6: Estimated (dead reckoning) Mode 7: Manual Input Mode 8: Simulator Mode
7	Satellites Used	08	Number of satellites in use, (00 ~ 12)
8	HDOP	1.1	Horizontal dilution of precision, (00.0 ~ 99.9)
9	Altitude	108.7	mean sea level (geoid), (-9999.9 ~ 17999.9)
10	Geoid Separation		Geoid separation in meters according to WGS-84 ellipsoid (-999.9 ~ 9999.9)
11	DGPS Age		Age of DGPS data since last valid RTCM transmission in xxx format (seconds) NULL when DGPS not used
12	DGPS Station ID	0000	Differential reference station ID, 0000 ~ 1023 NULL when DGPS not used
13	Checksum	0E	

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The checksum is the exclusive OR of all characters between '\$' and '*'.

9.2 GLL - LATITUDE AND LONGITUDE, WITH TIME OF POSITION FIX AND STATUS

Latitude and longitude of current position, time, and status.

Structure:

\$GPGLL,ddmm.mmmm,a,dddmm.mmmm,a,hhmmss.sss,A,a*hh<CR><LF>

1 2 3 4 5 6 7 8

Example:

\$GPGLL,4250.5589,S,14718.5084,E,092204.999,A,A*2D<CR><LF>

Field	Name	Example	Description
1	Latitude	4250.5589	Latitude in ddmm.mmmm format Leading zeros transmitted
2	N/S Indicator	S	Latitude hemisphere indicator 'N' = North 'S' = South
3	Longitude	14718.5084	Longitude in dddmm.mmmm format Leading zeros transmitted
4	E/W Indicator	E	Longitude hemisphere indicator 'E' = East 'W' = West
5	UTC Time	092204.999	UTC time in hhmmss.sss format (000000.00 ~ 235959.99)
6	Status	A	Status, 'A' = Data valid, 'V' = Data not valid
7	Mode Indicator	A	Mode indicator 'N' = Data not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode 'M' = Manual input mode 'S' = Simulator mode
8	Checksum	2D	

9.3 GSA - GPS DOP AND ACTIVE SATELLITES

GPS receiver operating mode, satellites used in the navigation solution reported by the GGA or GNS sentence and DOP values.

Structure:

\$GPGSA,A,x,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,x.x,x.x,x.x*hh<CR><LF>
1 2 3 3 3 3 3 3 3 3 3 3 3 3 4 5 6 7

Example:

\$GPGSA,A,3,01,20,19,13,,,,,,40.4,24.4,32.2*0A<CR><LF>

Field	Name	Example	Description
1	Mode	A	Mode 'M' = Manual, forced to operate in 2D or 3D mode 'A' = Automatic, allowed to automatically switch 2D/3D
2	Mode	3	Fix type 1 = Fix not available 2 = 2D 3 = 3D
3	Satellite used 1~12	01,20,19,13,,,,, ,,,,	Satellite ID number, 01 to 32, of satellite used in solution, up to 12 transmitted
4	PDOP	40.4	Position dilution of precision (00.0 to 99.9)
5	HDOP	24.4	Horizontal dilution of precision (00.0 to 99.9)
6	VDOP	32.2	Vertical dilution of precision (00.0 to 99.9)
7	Checksum	0A	

9.4 GSV - GPS SATELLITE IN VIEW

Number of satellites in view, PRN number, elevation angle, azimuth angle, and C/No. Four satellites details are transmitted per message. Additional satellite in view information is send in subsequent GSV messages.

Structure:

\$GPGSV,x,x,xx,xx,xx,xxx,xx,...,xx,xx,xxx,xx *hh<CR><LF>
1 2 3 4 5 6 7 4 5 6 7 8

Example:

\$GPGSV,3,1,09,28,81,225,41,24,66,323,44,20,48,066,43,17,45,336,41*78<CR><LF>

\$GPGSV,3,2,09,07,36,321,45,04,36,257,39,11,20,050,41,08,18,208,43*77<CR><LF>

Field	Name	Example	Description
1	Number of message	3	Total number of GSV messages to be transmitted (1-3)
2	Sequence number	1	Sequence number of current GSV message
3	Satellites in view	09	Total number of satellites in view (00 ~ 12)
4	Satellite ID	28	Satellite ID number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120)
5	Elevation	81	Satellite elevation in degrees, (00 ~ 90)
6	Azimuth	225	Satellite azimuth angle in degrees, (000 ~ 359)
7	SNR	41	C/No in dB (00 ~ 99) Null when not tracking
8	Checksum	78	

9.5 RMC - RECOMMENDED MINIMUM SPECIFIC GPS/TRANSIT DATA

Time, date, position, course and speed data provided by a GNSS navigation receiver.

Structure:

\$GPRMC,1 2 3 4 5 6 7 8 9 10 11 12 13
hhmmss.sss,A,dddmm.mmmm,a,dddmm.mmmm,a,x.x,x.x,ddmmyy,x.x,a,a*hh<CR><LF>

Example:

\$GPRMC,092204.999,A,4250.5589,S,14718.5084,E,0.00,89.68,211200,,A*25<CR><LF>

Field	Name	Example	Description
1	UTC time	092204.999	UTC time in hhmmss.sss format (000000.00 ~ 235959.999)
2	Status	A	Status 'V' = Navigation receiver warning 'A' = Data Valid
3	Latitude	4250.5589	Latitude in dddmm.mmmm format Leading zeros transmitted
4	N/S indicator	S	Latitude hemisphere indicator 'N' = North 'S' = South
5	Longitude	14718.5084	Longitude in dddmm.mmmm format Leading zeros transmitted
6	E/W Indicator	E	Longitude hemisphere indicator 'E' = East 'W' = West
7	Speed over ground	000.0	Speed over ground in knots (000.0 ~ 999.9)
8	Course over ground	000.0	Course over ground in degrees (000.0 ~ 359.9)
9	UTC Date	211200	UTC date of position fix, ddmmyy format
10	Magnetic variation		Magnetic variation in degrees (000.0 ~ 180.0)
11	Magnetic Variation		Magnetic variation direction 'E' = East 'W' = West
12	Mode indicator	A	Mode indicator 'N' = Data not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode 'M' = Manual input mode 'S' = Simulator mode
13	checksum	25	

9.6 VTG - COURSE OVER GROUND AND GROUND SPEED

The Actual course and speed relative to the ground.

Structure:

GPVTG,x.x,T,x.x,M,x.x,N,x.x,K,a*hh<CR><LF>
1 2 3 4 5 6

Example:

\$GPVTG,89.68,T,,M,0.00,N,0.0,K,A*5F<CR><LF>

Field	Name	Example	Description
1	Course	89.68	True course over ground in degrees (000.0 ~ 359.9)
2	Course		Magnetic course over ground in degrees (000.0 ~ 359.9)
3	Speed	0.00	Speed over ground in knots (000.0 ~ 999.9)
4	Speed	0.00	Speed over ground in kilometers per hour (0000.0 ~ 1800.0)
5	Mode	A	Mode indicator 'N' = not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode 'M' = Manual input mode 'S' = Simulator mode
6	Checksum	5F	

9.7 ZDA - TIME AND DATE

Structure:

\$GPRMC,hhmmss.sss,dd,mm.yyyy, , ,xxx<CR><LF>
1 2 3 4 5 6 7

Example:

\$GPZDA,104548.04,25,03,2004,,*6C<CR><LF>

Field	Name	Example	Description
1	UTC time	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	UTC time: day	25	UTC time: day (01 ... 31)
3	UTC time: month	03	UTC time: month (01 ... 12)
4	UTC time: year	2004	UTC time: year (4 digit year)
5			Local zone hour Not being output by the receiver (NULL)
6			Local zone minutes Not being output by the receiver (NULL)
7	6C	6C	Checksum

9.8 BINARY MESSAGES

See *Binary Message Protocol User's Guide* for detailed descriptions.