EN: This Datasheet/Document is presented by the manufacturer.

Please visit our website for pricing and availability at www.hestore.hu.

AMC1301 Precision, ±250-mV Input, 3-µs Delay, Reinforced Isolated Amplifier

1 Features

- ±250-mV Input Voltage Range Optimized for Current Measurement Using Shunt Resistors
- Low Offset Error and Drift: ±200 µV at 25°C, ± 3 µV/°C
- Fixed Gain: 8.2
- Very Low Gain Error and Drift: ±0.3% at 25°C, ± 50 ppm/°C
- Very Low Nonlinearity and Drift: 0.03%, 1 ppm/°C
- 3.3-V Operation on High-Side and Low-Side
- System-Level Diagnostic Features
- Safety-Related Certifications:
  - 7000-V_{PK} Reinforced Isolation per DIN V VDE V 0884-10 (VDE V 0884-10): 2006-12
  - 5000-V_{RMS} Isolation for 1 Minute per UL1577
  - CAN/CSA No. 5A-Component Acceptance Service Notice, IEC 60950-1, and IEC 60065 End Equipment Standards
- Fully Specified Over the Extended Industrial Temperature Range

2 Applications

- Shunt-Resistor-Based Current Sensing In:
  - Motor Drives
  - Frequency Inverters
  - Uninterruptible Power Supplies
- Isolated Voltage Sensing

3 Description

The AMC1301 device is a precision, isolated amplifier with an output separated from the input circuitry by an isolation barrier that is highly resistant to magnetic interference. This barrier is certified to provide reinforced galvanic isolation of up to 7 kV_{PEAK} according to VDE V 0884-10 and UL1577. Used in conjunction with isolated power supplies, this device prevents noise currents on a high common-mode voltage line from entering the local ground and interfering with or damaging sensitive circuitry.

The input of the AMC1301 is optimized for direct connection to shunt resistors or other low voltage-level signal sources. The excellent performance of the device supports accurate current control resulting in system-level power savings and, especially in motor control applications, lower torque ripple. The integrated common-mode overvoltage and missing high-side supply voltage detection features of the AMC1301 simplify system-level design and diagnostics.

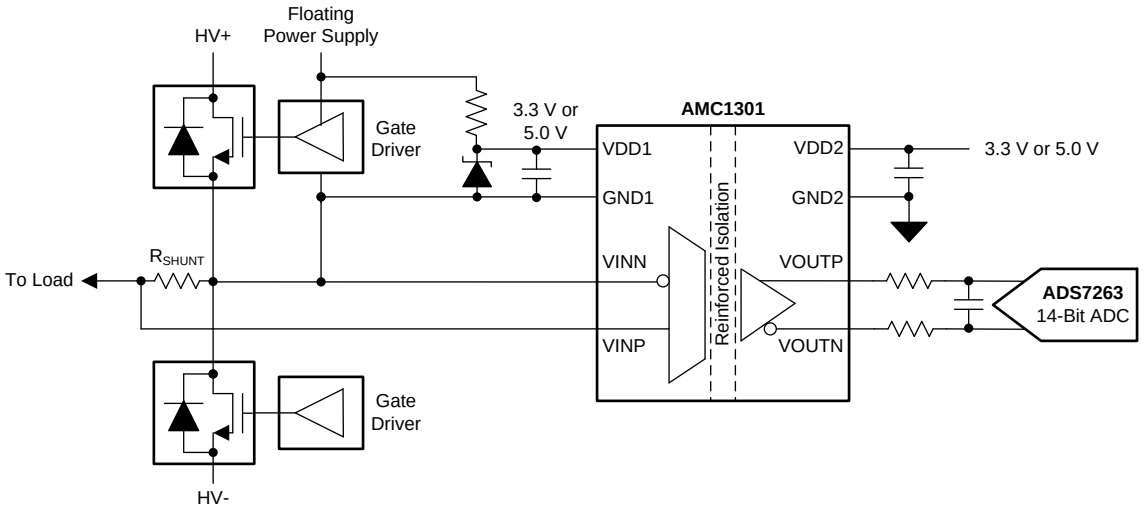
The AMC1301 is fully specified over the extended industrial temperature range of –40°C to +125°C and is available in a wide-body 8-pin SOIC (DWV) package. The AMC1301S is specified over the temperature range of –55°C to +125°C.

Device Information[1]

PART NUMBER	PACKAGE	BODY SIZE (NOM)
AMC1301	SOIC (8)	5.85 mm × 7.50 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic



An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

Table of Contents

1 **Features** ... 1
2 **Applications** ... 1
3 **Description** ... 1
4 **Revision History** ... 2
5 **Device Comparison Table** ... 4
6 **Pin Configuration and Functions** ... 4
7 **Specifications** ... 5
7.1 Absolute Maximum Ratings ... 5
7.2 ESD Ratings ... 5
7.3 Recommended Operating Conditions ... 5
7.4 Thermal Information ... 5
7.5 Power Ratings ... 5
7.6 Insulation Specifications ... 6
7.7 Safety-Related Certifications ... 7
7.8 Safety Limiting Values ... 7
7.9 Electrical Characteristics ... 7
7.10 Insulation Characteristics Curves ... 9
7.11 Typical Characteristics ... 10
8 **Parameter Measurement Information** ... 17
8.1 Timing Diagrams ... 17
9 **Detailed Description** ... 18
9.1 Overview ... 18
9.2 Functional Block Diagram ... 18
9.3 Feature Description ... 18
9.4 Device Functional Modes ... 19
10 **Application and Implementation** ... 20
10.1 Application Information ... 20
10.2 Typical Applications ... 20
10.3 Do's and Don'ts ... 24
11 **Power Supply Recommendations** ... 25
12 **Layout** ... 26
12.1 Layout Guidelines ... 26
12.2 Layout Example ... 26
13 **Device and Documentation Support** ... 27
13.1 Documentation Support ... 27
13.2 Related Links ... 27
13.3 Receiving Notification of Documentation Updates 27
13.4 Community Resources ... 27
13.5 Trademarks ... 27
13.6 Electrostatic Discharge Caution ... 27
13.7 Glossary ... 27
14 **Mechanical, Packaging, and Orderable Information** ... 28

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision D (January 2017) to Revision E **Page**

- Added AMC1301S device to document ... 1
- Added last sentence to *Description* section ... 1
- Added *Device Comparison Table* section ... 4
- Added AMC1301S row to T_A parameter in *Recommended Operating Conditions* table ... 5
- Added AMC1301S row to *Climatic category* parameter of *Insulation Specifications* table ... 6
- Added AMC1301S temperature range to conditions statement of *Electrical Characteristics* table ... 7
- Added AMC1301S row to TCV_{OS} parameter in *Electrical Characteristics* table ... 7
- Changed I_{IB} parameter specification and conditions ... 7
- Added AMC1301S row to TCE_G parameter in *Electrical Characteristics* table ... 8
- Changed all temperature plots in Typical Characteristics section to cover –55°C for the AMC1301S and added respective footnote ... 10
- Changed *Input Bias Current vs Common-Mode Input Voltage* figure to align with new test condition ... 11
- Changed *Input Bias Current vs High-Side Supply Voltage* figure to align with new test condition ... 11
- Changed *Input Bias Current vs Temperature* figure to align with new test condition ... 12
- Changed legend of *Output Voltage vs Input Voltage* figure, V_{OUTP} is now red and V_{OUTN} is now black ... 13

Changes from Revision C (September 2016) to Revision D **Page**

- Changed *VDD1* to *VDD2* in test conditions of I_{DD2} and P_{DD2} parameters of *Electrical Characteristics* table ... 8
- Changed *VDD2* to *VDD1* in conditions of *Gain Error Histogram* figures ... 12

Copyright © 2016–2018, Texas Instruments Incorporated

Changes from Revision B (June 2016) to Revision C **Page**

- Changed *12-Bit ADC* to *14-Bit ADC* in *Simplified Schematic* figure ... 1
- Changed maximum specification of *Supply voltage* row in *Absolute Maximum Ratings* table ... 5
- Changed *12-Bit ADC* to *14-Bit ADC* in *Zener-Diode Based, High Side Power Supply* figure in *Power Supply Recommendations* section ... 25

Changes from Revision A (April 2016) to Revision B **Page**

- Changed Features bullet from "Safety and Regulatory Approvals" to "Safety-Related Certifications" ... 1
- Changed *Simplified Schematic* figure in *Device Information* table ... 1
- Changed section title from "Regulatory Information" to "Safety-Related Certifications" ... 7
- Changed V_{CM} test conditions in *Electrical Characteristics* table ... 7
- Added V_{IN} footnote to *Electrical Characteristics* table ... 7
- Changed V_{IN} test conditions in *Electrical Characteristics* table ... 7
- Changed V_{IN} units in *Electrical Characteristics* table ... 7
- Changed common-mode rejection ratio test condition in *Electrical Characteristics* table ... 7
- Changed R_{IN} parameter information in *Electrical Characteristics* table ... 7
- Changed output noise equation in *Electrical Characteristics* table ... 8
- Deleted "Safety and" from *Insulation Characteristics Curves* section title ... 9
- Changed *Using the AMC1301 for Current Sensing in Frequency Inverters* figure in *Application Information* ... 20
- Changed *Zener-Diode Based, High Side Power Supply* figure in *Power Supply Recommendations* ... 25
- Added a paragraph and changed the formatting of the *Related Documentation* section ... 27

Changes from Original (April 2016) to Revision A **Page**

- Released to production ... 1

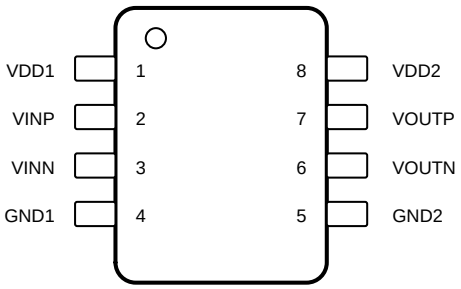
Copyright © 2016–2018, Texas Instruments Incorporated

5 Device Comparison Table

PARAMETER	AMC1301S	AMC1301
Specified ambient temperature, T_A	–55°C to +125°C	–40°C to +125°C
Input offset drift, TCV_{OS}	±4 µV/°C (max)	±3 µV/°C (max)
Gain error drift, TCE_G	±60 ppm/°C (max)	±50 ppm/°C (max)

6 Pin Configuration and Functions

DWV Package
8-Pin SOIC
Top View



Not to scale

Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
GND1	4	—	High-side analog ground
GND2	5	—	Low-side analog ground
VDD1	1	—	High-side power supply, 3.0 V to 5.5 V. See the *Power Supply Recommendations* section for decoupling recommendations.
VDD2	8	—	Low-side power supply, 3.0 V to 5.5 V. See the *Power Supply Recommendations* section for decoupling recommendations.
VINN	3	I	Inverting analog input
VINP	2	I	Noninverting analog input
VOUTN	6	O	Inverting analog output
VOUTP	7	O	Noninverting analog output

Copyright © 2016–2018, Texas Instruments Incorporated

7 Specifications

7.1 Absolute Maximum Ratings(1)

	MIN	MAX	UNIT
Supply voltage, VDD1 to GND1 or VDD2 to GND2	–0.3	7	V
Analog input voltage at VINP, VINN	GND1 – 6	VDD1 + 0.5	V
Input current to any pin except supply pins	–10	10	mA
Junction temperature, T_J		150	°C
Storage temperature, T_{stg}	–65	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

7.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101(2)	±1000	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating ambient temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
VDD1	High-side supply voltage (VDD1 to GND1)		3.0	5.0	5.5	V
VDD2	Low-side supply voltage (VDD2 to GND2)		3.0	3.3	5.5	V
T_A	Operating ambient temperature	AMC1301	–40		125	°C
		AMC1301S	–55		125	°C

7.4 Thermal Information

THERMAL METRIC(1)		AMC1301 DWV (SOIC) 8 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	110.1	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	51.7	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	66.4	°C/W
ψ_{JT}	Junction-to-top characterization parameter	16.0	°C/W
ψ_{JB}	Junction-to-board characterization parameter	64.5	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.

7.5 Power Ratings

PARAMETER		TEST CONDITIONS	VALUE	UNIT
P_D	Maximum power dissipation (both sides)	VDD1 = VDD2 = 5.5 V	81.4	mW
P_{D1}	Maximum power dissipation (high-side supply)		45.65	mW
P_{D2}	Maximum power dissipation (low-side supply)		35.75	mW

Copyright © 2016–2018, Texas Instruments Incorporated

7.6 Insulation Specifications

over operating ambient temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	VALUE	UNIT
GENERAL				
CLR	External clearance(1)	Shortest pin-to-pin distance through air	≥ 9	mm
CPG	External creepage(1)	Shortest pin-to-pin distance across the package surface	≥ 9	mm
DTI	Distance through insulation	Minimum internal gap (internal clearance) of the double insulation (2 × 0.0135 mm)	≥ 0.027	mm
CTI	Comparative tracking index	DIN EN 60112 (VDE 0303-11); IEC 60112	≥ 600	V
	Material group	According to IEC 60664-1	I	
	Overvoltage category per IEC 60664-1	Rated mains voltage ≤ 300 V_{RMS}	I-IV	
		Rated mains voltage ≤ 600 V_{RMS}	I-III	
		Rated mains voltage ≤ 1000 V_{RMS}	I-II	
DIN V VDE V 0884-10 (VDE V 0884-10): 2006-12(2)				
V_{IORM}	Maximum repetitive peak isolation voltage	At ac voltage (bipolar)	1500	V_{PK}
V_{IOWM}	Maximum-rated isolation working voltage	At ac voltage (sine wave)	1000	V_{RMS}
		At dc voltage	1500	V_{DC}
V_{IOTM}	Maximum transient isolation voltage	$V_{TEST} = V_{IOTM}$, t = 60 s (qualification test)	7000	V_{PK}
		$V_{TEST} = 1.2 \times V_{IOTM}$, t = 1 s (100% production test)	8400	
V_{IOSM}	Maximum surge isolation voltage(3)	Test method per IEC 60065, 1.2/50-µs waveform, $V_{TEST} = 1.6 \times V_{IOSM} = 10000\ V_{PK}$ (qualification)	6250	V_{PK}
q_{pd}	Apparent charge(4)	Method a, after input/output safety test subgroup 2 / 3, $V_{ini} = V_{IOTM}$, t_{ini} = 60 s, $V_{pd(m)} = 1.2 \times V_{IORM} = 1800\ V_{PK}$, t_m = 10 s	≤ 5	pC
		Method a, after environmental tests subgroup 1, $V_{ini} = V_{IOTM}$, t_{ini} = 60 s, $V_{pd(m)} = 1.6 \times V_{IORM} = 2400\ V_{PK}$, t_m = 10 s	≤ 5	
		Method b1, at routine test (100% production) and preconditioning (type test), $V_{ini} = V_{IOTM}$, t_{ini} = 1 s, $V_{pd(m)} = 1.875 \times V_{IORM} = 2812.5\ V_{PK}$, t_m = 1 s	≤ 5	
C_{IO}	Barrier capacitance, input to output(5)	V_{IO} = 0.5 V_{PP} at 1 MHz	1.2	pF
R_{IO}	Insulation resistance, input to output(5)	V_{IO} = 500 V at T_S = 150°C	$> 10^9$	Ω
	Pollution degree		2	
	Climatic category	AMC1301	40/125/21	
		AMC1301S	55/125/21	
UL1577				
V_{ISO}	Withstand isolation voltage	$V_{TEST} = V_{ISO} = 5000\ V_{RMS}$ or 7000 V_{DC}, t = 60 s (qualification), $V_{TEST} = 1.2 \times V_{ISO} = 6000\ V_{RMS}$, t = 1 s (100% production test)	5000	V_{RMS}

(1) Apply creepage and clearance requirements according to the specific equipment isolation standards of an application. Care must be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed circuit board (PCB) do not reduce this distance. Creepage and clearance on a PCB become equal in certain cases. Techniques such as inserting grooves and ribs on the PCB are used to help increase these specifications.
(2) This coupler is suitable for *safe electrical insulation* only within the safety ratings. Compliance with the safety ratings shall be ensured by means of suitable protective circuits.
(3) Testing is carried out in air or oil to determine the intrinsic surge immunity of the isolation barrier.
(4) Apparent charge is electrical discharge caused by a partial discharge (pd).
(5) All pins on each side of the barrier are tied together, creating a two-pin device.

Copyright © 2016–2018, Texas Instruments Incorporated

7.7 Safety-Related Certifications

VDE	UL
Certified according to DIN V VDE V 0884-10 (VDE V 0884-10): 2006-12, DIN EN 60950-1 (VDE 0805 Teil 1): 2014-08, and DIN EN 60065 (VDE 0860): 2005-11	Recognized under 1577 component recognition and CSA component acceptance NO 5 programs
Reinforced insulation	Single protection
Certificate number: 40040142	File number: E181974

7.8 Safety Limiting Values

Safety limiting intends to prevent potential damage to the isolation barrier upon failure of input or output (I/O) circuitry. A failure of the I/O may allow low resistance to ground or the supply and, without current limiting, dissipate sufficient power to overheat the die and damage the isolation barrier, potentially leading to secondary system failures.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_S	Safety input, output, or supply current	$R_{\theta JA}$ = 110.1°C/W, V_I = 5.5 V, T_J = 150°C, T_A = 25°C			206	mA
		$R_{\theta JA}$ = 110.1°C/W, V_I = 3.6 V, T_J = 150°C, T_A = 25°C			315	
P_S	Safety input, output, or total power(1)	$R_{\theta JA}$ = 110.1°C/W, T_J = 150°C, T_A = 25°C			1135	mW
T_S	Maximum safety temperature				150	°C

(1) Input, output, or the sum of input and output power must not exceed this value.

The maximum safety temperature is the maximum junction temperature specified for the device. The power dissipation and junction-to-air thermal impedance of the device installed in the application hardware determines the junction temperature. The assumed junction-to-air thermal resistance in the *Thermal Information* table is that of a device installed on a high-K test board for leaded surface-mount packages. The power is the recommended maximum input voltage times the current. The junction temperature is then the ambient temperature plus the power times the junction-to-air thermal resistance.

7.9 Electrical Characteristics

minimum and maximum specifications apply from T_A = –40°C to +125°C (for AMC1301S: T_A = –55°C to +125°C), VDD1 = 3.0 V to 5.5 V, VDD2 = 3.0 V to 5.5 V, VINP = –250 mV to +250 mV, and VINN = 0 V (unless otherwise noted); typical specifications are at T_A = 25°C, VDD1 = 5 V, and VDD2 = 3.3 V

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ANALOG INPUT						
$V_{Clipping}$	Differential input voltage before clipping output	VINP – VINN		±302.7		mV
V_{FSR}	Specified linear differential full-scale	VINP – VINN	–250		250	mV
V_{CM}	Specified common-mode input voltage	(VINP + VINN) / 2 to GND1	–0.16		VDD1 – 2.1	V
	Absolute common-mode input voltage(1)	(VINN + VINP) / 2 to GND1	–2		VDD1	V
V_{CMov}	Common-mode overvoltage detection level		VDD1 – 2			V
V_{OS}	Input offset voltage	Initial, at T_A = 25°C, VINP = VINN = GND1	–200	±50	200	µV
TCV_{OS}	Input offset drift	AMC1301	–3	±1	3	µV/°C
		AMC1301S	–4	±1	4	
CMRR	Common-mode rejection ratio	f_{IN} = 0 Hz, $V_{CM\ min} \le V_{CM} \le V_{CM\ max}$		–93		dB
		f_{IN} = 10 kHz, $V_{CM\ min} \le V_{CM} \le V_{CM\ max}$		–93		
C_{IND}	Differential input capacitance			1		pF
R_{IN}	Single-ended input resistance	VINN = GND1		18		kΩ
R_{IND}	Differential input resistance			22		kΩ
I_{IB}	Input bias current	VINP = VINN = GND1, $I_{IB} = (I_{IBP} + I_{IBN}) / 2$	–41	–30	–24	µA
TCI_{IB}	Input bias current drift			1		nA/°C
BW_{IN}	Input bandwidth			1000		kHz

(1) Steady-state voltage supported by the device in case of a system failure. See specified common-mode input voltage V_{CM} for normal operation. Observe analog input voltage range as specified in *Absolute Maximum Ratings*.

Copyright © 2016–2018, Texas Instruments Incorporated

Electrical Characteristics (continued)

minimum and maximum specifications apply from T_A = –40°C to +125°C (for AMC1301S: T_A = –55°C to +125°C), VDD1 = 3.0 V to 5.5 V, VDD2 = 3.0 V to 5.5 V, VINP = –250 mV to +250 mV, and VINN = 0 V (unless otherwise noted); typical specifications are at T_A = 25°C, VDD1 = 5 V, and VDD2 = 3.3 V

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ANALOG OUTPUT						
	Nominal gain			8.2		
E_G	Gain error	Initial, at T_A = 25°C	–0.3%	±0.05%	0.3%	
TCE_G	Gain error drift	AMC1301	–50	±15	50	ppm/°C
		AMC1301S	–60	±15	60	
	Nonlinearity		–0.03%	±0.01%	0.03%	
	Nonlinearity drift			1		ppm/°C
THD	Total harmonic distortion	f_{IN} = 10 kHz		–87		dB
	Output noise	VINP = VINN = GND1, f_{IN} = 0 Hz, BW = 100 kHz		220		μV_{RMS}
SNR	Signal-to-noise ratio	f_{IN} = 1 kHz, BW = 10 kHz	80	84		dB
		f_{IN} = 10 kHz, BW = 100 kHz		71		
PSRR	Power-supply rejection ratio	vs VDD1, at dc		–94		dB
		vs VDD1, 100-mV and 10-kHz ripple		–90		
		vs VDD2, at dc		–100		
		vs VDD2, 100-mV and 10-kHz ripple		–94		
t_r	Rise time	See Figure 45		2.0		µs
t_f	Fall time	See Figure 45		2.0		µs
	V_{IN} to V_{OUT} signal delay (50% – 10%)	See Figure 46, unfiltered output		0.7	2.0	µs
	V_{IN} to V_{OUT} signal delay (50% – 50%)	See Figure 46, unfiltered output		1.6	2.6	µs
	V_{IN} to V_{OUT} signal delay (50% – 90%)	See Figure 46, unfiltered output		2.5	3.0	µs
CMTI	Common-mode transient immunity	|GND1 – GND2| = 1 kV	15			kV/µs
V_{CMout}	Common-mode output voltage		1.39	1.44	1.49	V
	Output short-circuit current			±13		mA
R_{OUT}	Output resistance	on VOUTP or VOUTN		< 0.2		Ω
BW	Output bandwidth		190	210		kHz
$V_{FAILSAFE}$	Failsafe differential output voltage	$V_{CM} \geq V_{CMov}$, or VDD1 missing		–2.563	–2.545	V
POWER SUPPLY						
I_{DD1}	High-side supply current	3.0 V ≤ VDD1 ≤ 3.6 V		5.0	6.9	mA
		4.5 V ≤ VDD1 ≤ 5.5 V		5.9	8.3	
I_{DD2}	Low-side supply current	3.0 V ≤ VDD2 ≤ 3.6 V		4.4	5.6	mA
		4.5 V ≤ VDD2 ≤ 5.5 V		4.8	6.5	
P_{DD1}	High-side power dissipation	3.0 V ≤ VDD1 ≤ 3.6 V		16.5	24.84	mW
		4.5 V ≤ VDD1 ≤ 5.5 V		29.5	45.65	
P_{DD2}	Low-side power dissipation	3.0 V ≤ VDD2 ≤ 3.6 V		14.52	20.16	mW
		4.5 V ≤ VDD2 ≤ 5.5 V		24	35.75	

Copyright © 2016–2018, Texas Instruments Incorporated

7.10 Insulation Characteristics Curves

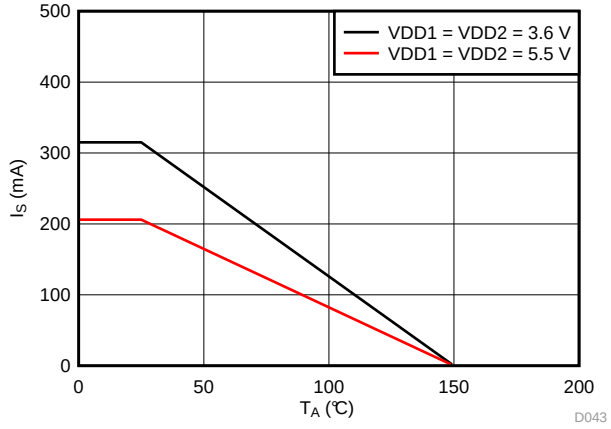


Figure 1. Thermal Derating Curve for Safety-Limiting Current per VDE

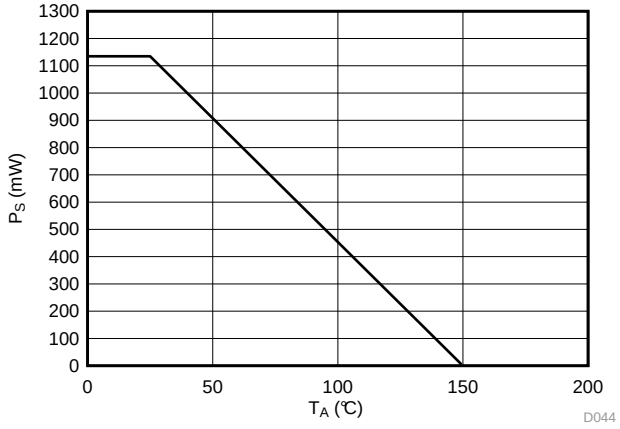
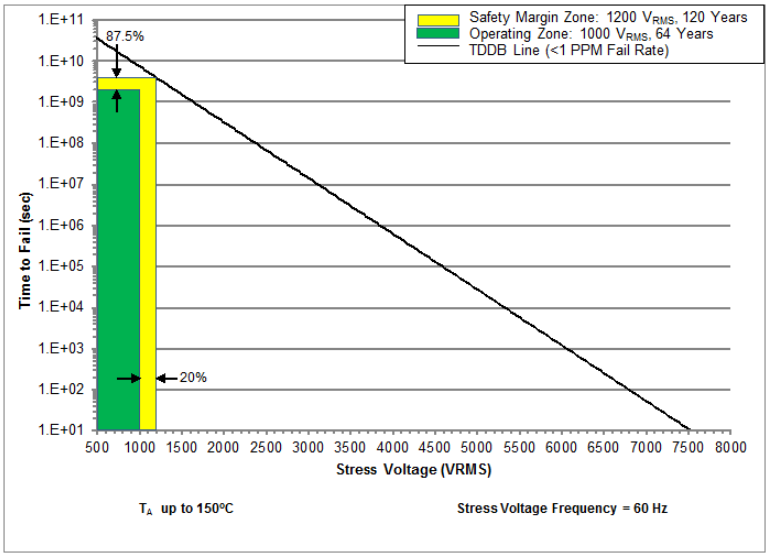


Figure 2. Thermal Derating Curve for Safety-Limiting Power per VDE



T_A up to 150°C, stress voltage frequency = 60 Hz

Figure 3. Reinforced Isolation Capacitor Lifetime Projection

7.11 Typical Characteristics

at VDD1 = 5 V, VDD2 = 3.3 V, VINP = –250 mV to 250 mV, VINN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)

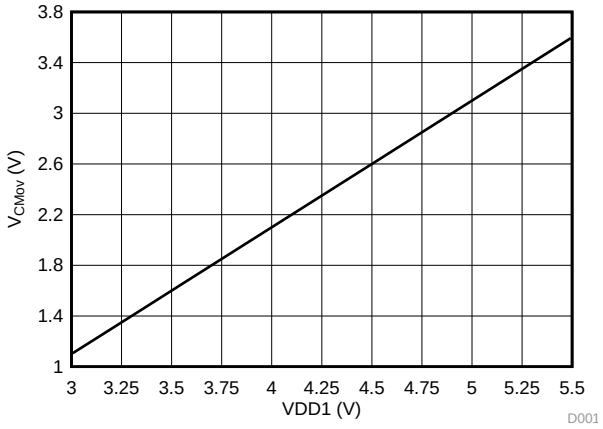
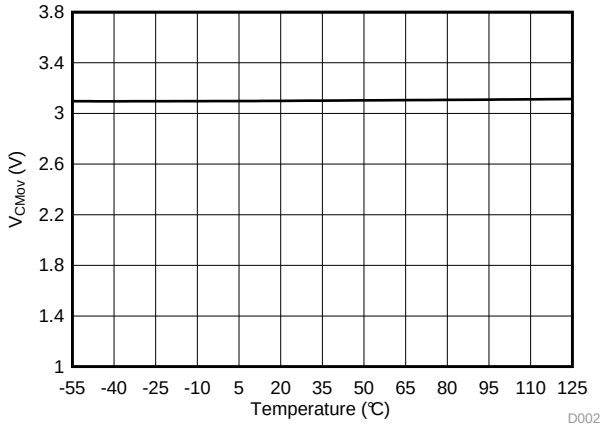
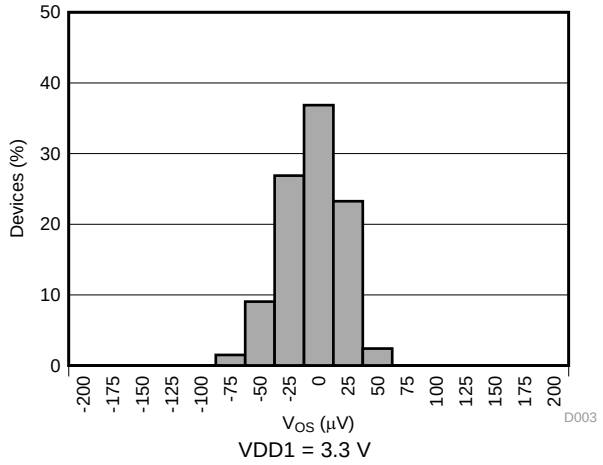


Figure 4. Common-Mode Overvoltage Detection Level vs High-Side Supply Voltage



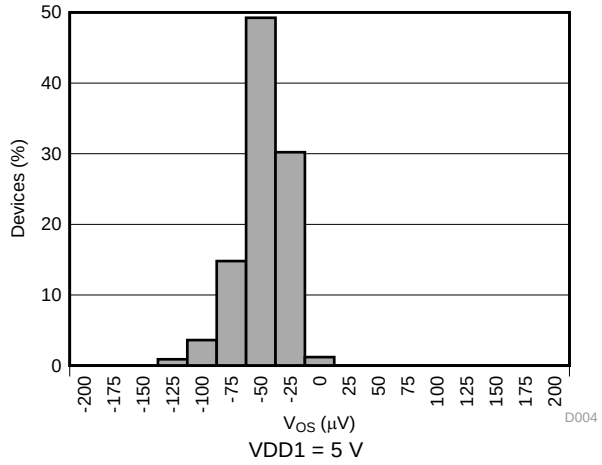
–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 5. Common-Mode Overvoltage Detection Level vs Temperature



VDD1 = 3.3 V

Figure 6. Input Offset Voltage Histogram



VDD1 = 5 V

Figure 7. Input Offset Voltage Histogram

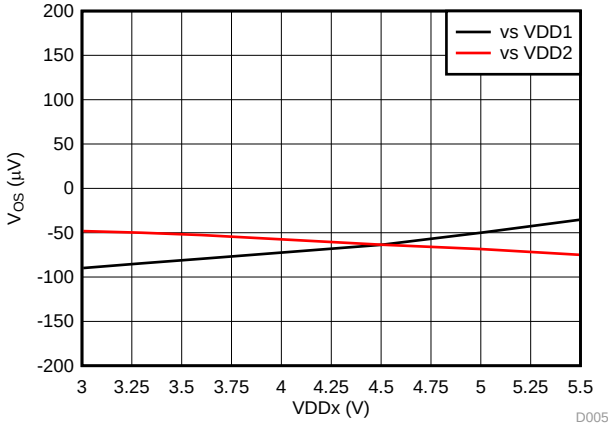
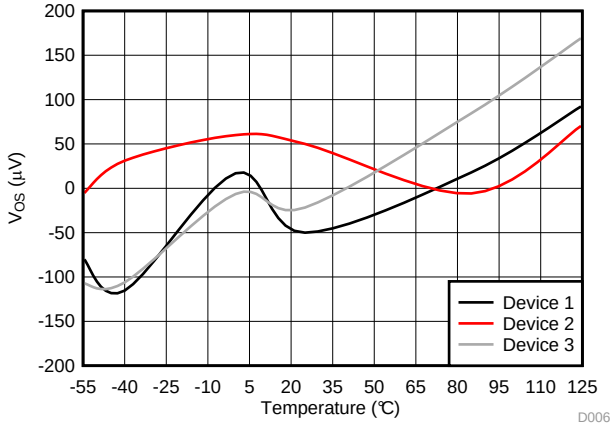


Figure 8. Input Offset Voltage vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 9. Input Offset Voltage vs Temperature

Copyright © 2016–2018, Texas Instruments Incorporated

Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, VINP = –250 mV to 250 mV, VINN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)

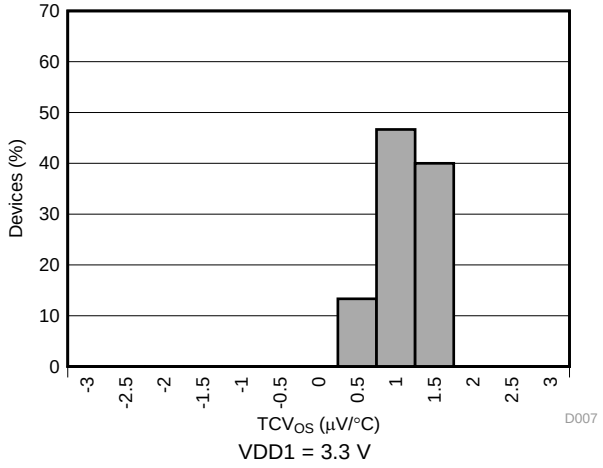


Figure 10. Input Offset Drift Histogram

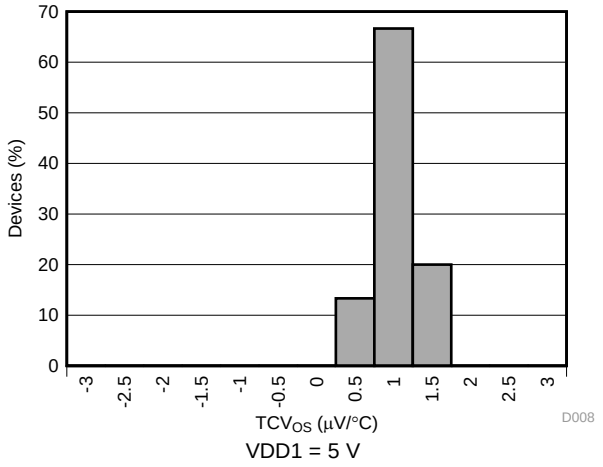


Figure 11. Input Offset Drift Histogram

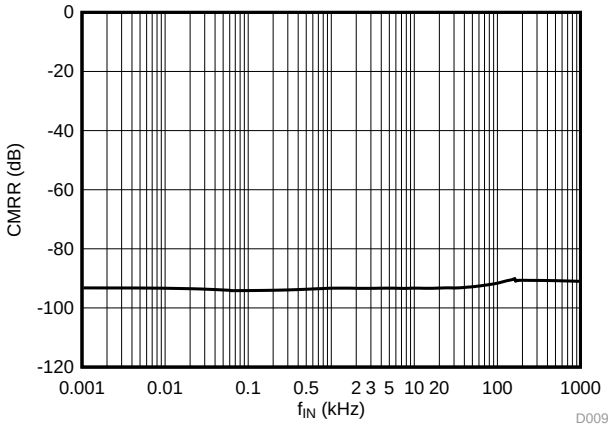


Figure 12. Common-Mode Rejection Ratio vs Input Frequency

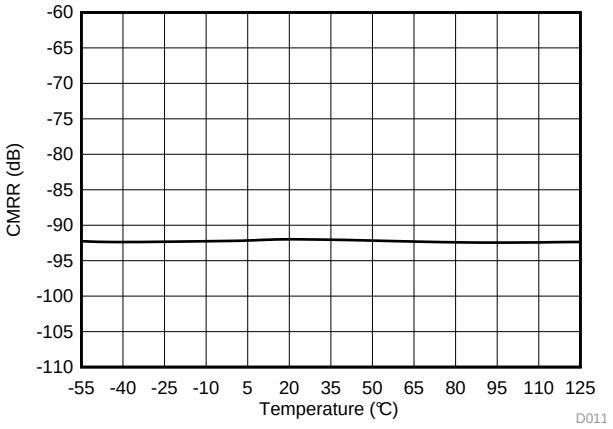


Figure 13. Common-Mode Rejection Ratio vs Temperature

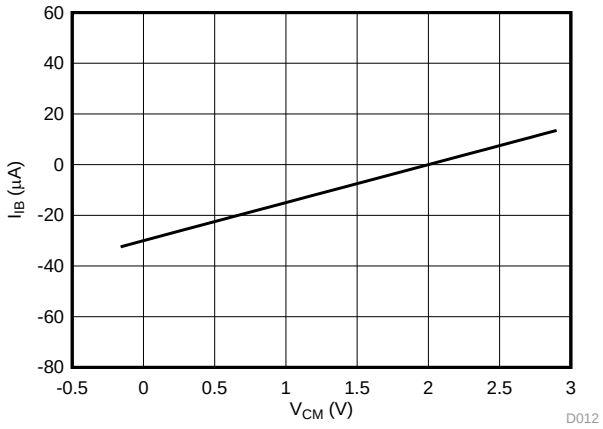


Figure 14. Input Bias Current vs Common-Mode Input Voltage

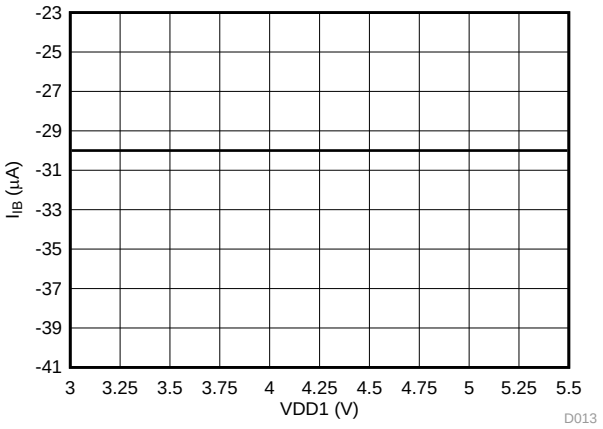
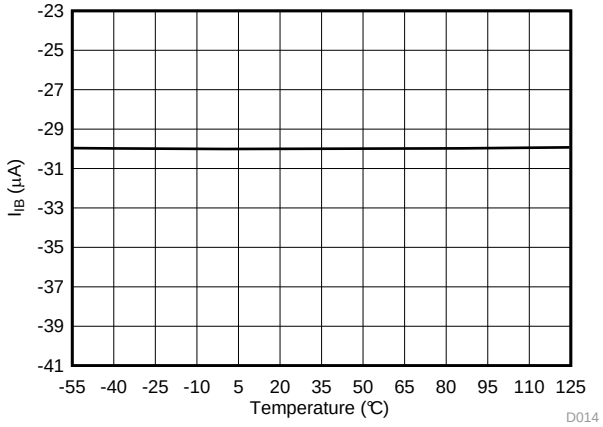


Figure 15. Input Bias Current vs High-Side Supply Voltage

Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, VINP = –250 mV to 250 mV, VINN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 16. Input Bias Current vs Temperature

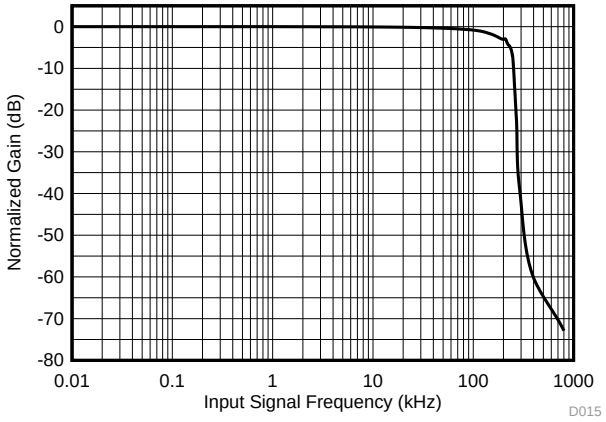
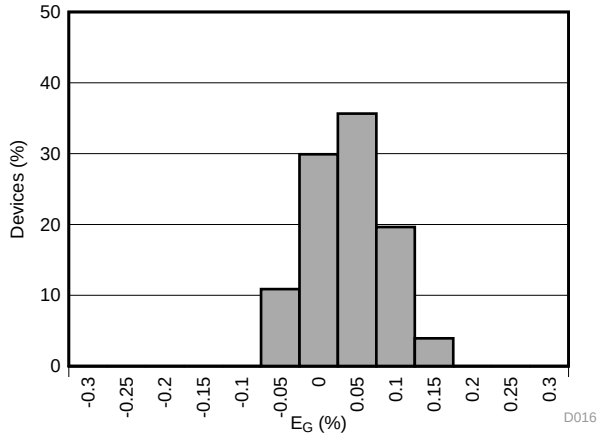
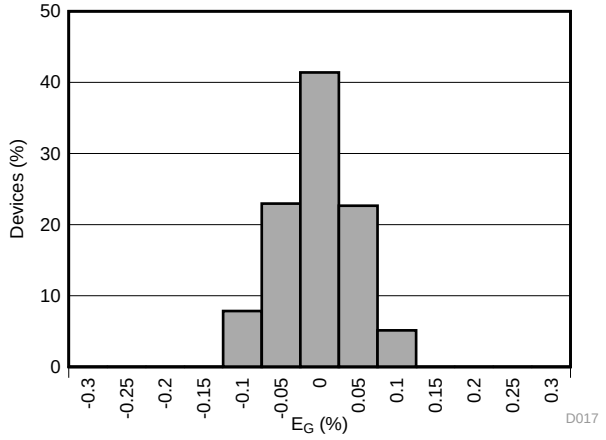


Figure 17. Normalized Gain vs Input Frequency



VDD1 = 3.3 V

Figure 18. Gain Error Histogram



VDD1 = 5 V

Figure 19. Gain Error Histogram

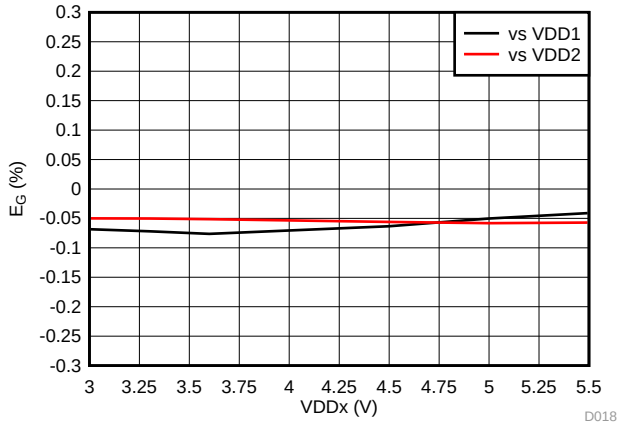
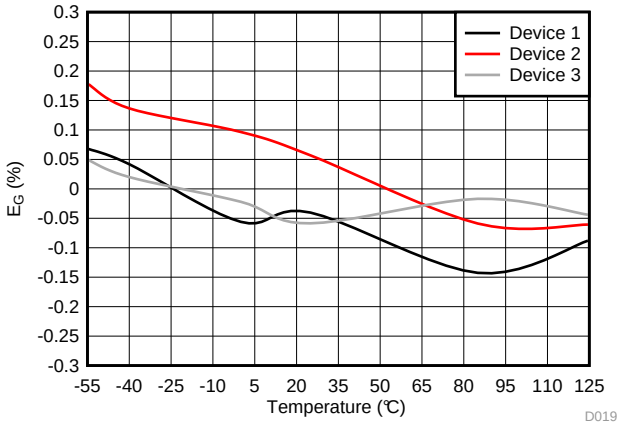


Figure 20. Gain Error vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 21. Gain Error vs Temperature

Copyright © 2016–2018, Texas Instruments Incorporated

Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, VINP = –250 mV to 250 mV, VINN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)

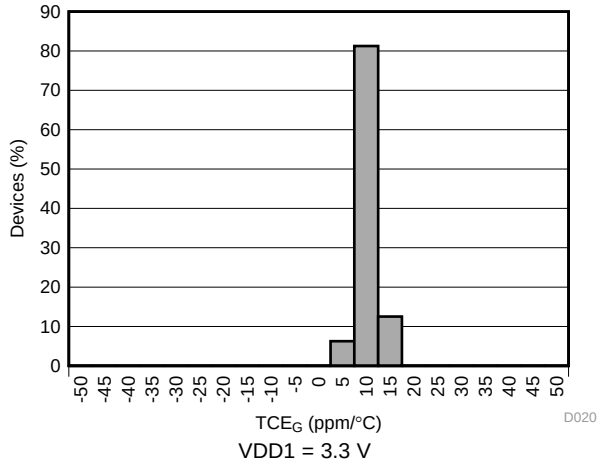


Figure 22. Gain Error Drift Histogram

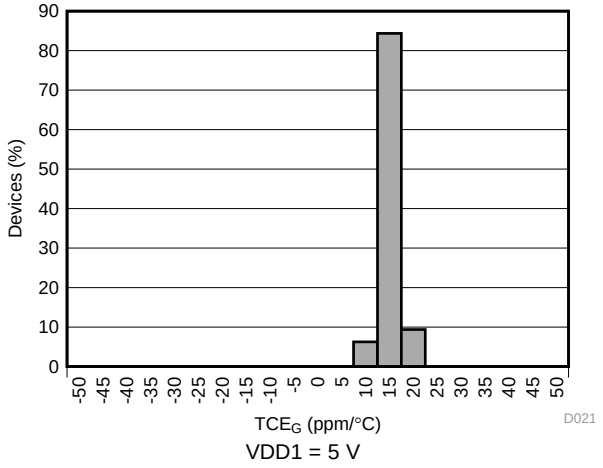


Figure 23. Gain Error Drift Histogram

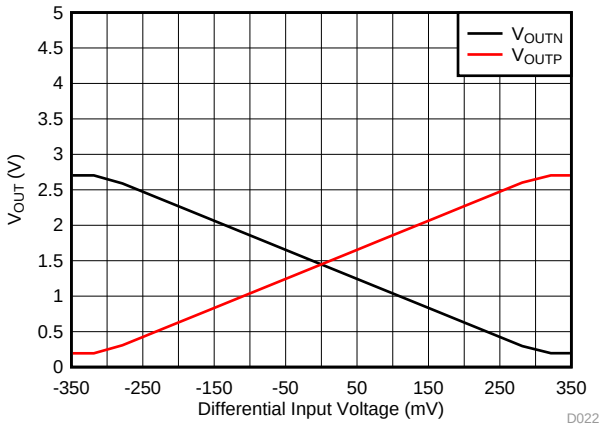


Figure 24. Output Voltage vs Input Voltage

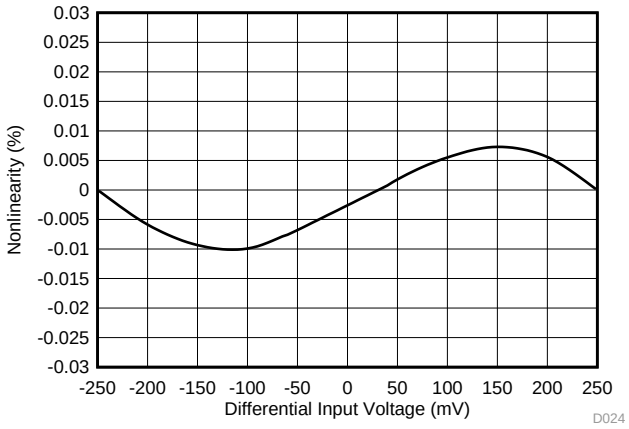


Figure 25. Nonlinearity vs Input Voltage

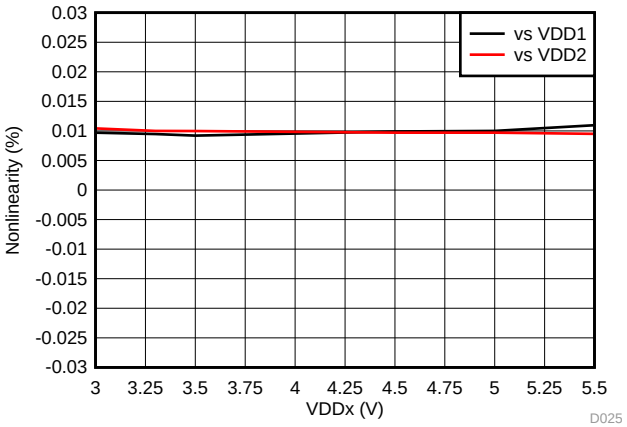
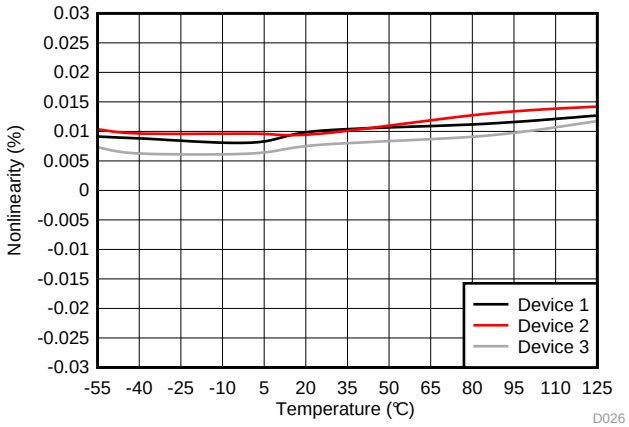


Figure 26. Nonlinearity vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 27. Nonlinearity vs Temperature

Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, VINP = –250 mV to 250 mV, VINN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)

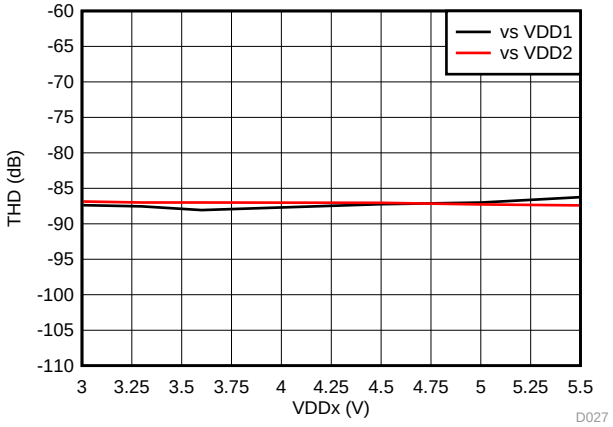
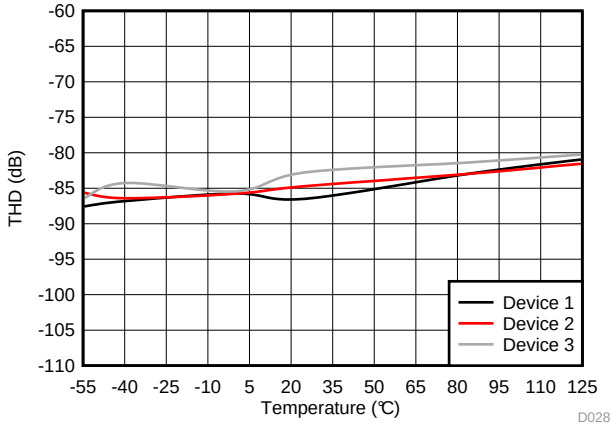


Figure 28. Total Harmonic Distortion vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 29. Total Harmonic Distortion vs Temperature

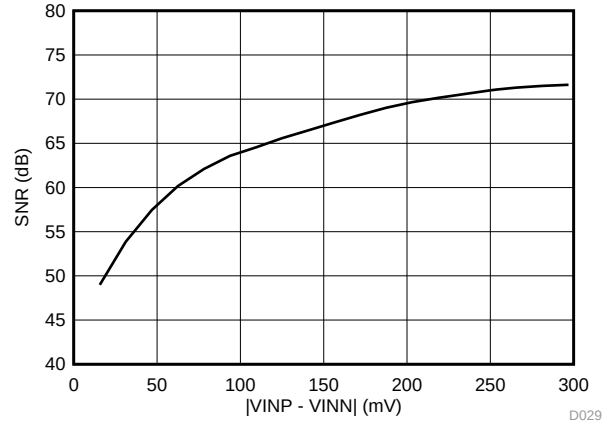


Figure 30. Signal-to-Noise Ratio vs Input Voltage

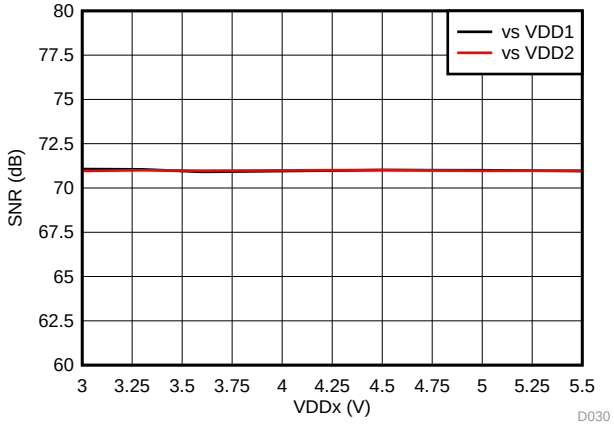
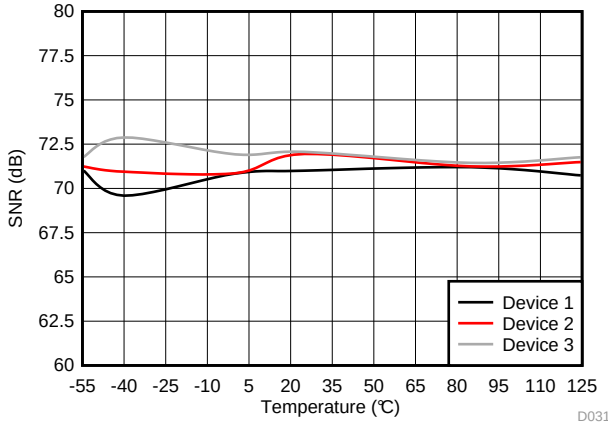


Figure 31. Signal-to-Noise Ratio vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 32. Signal-to-Noise Ratio vs Temperature

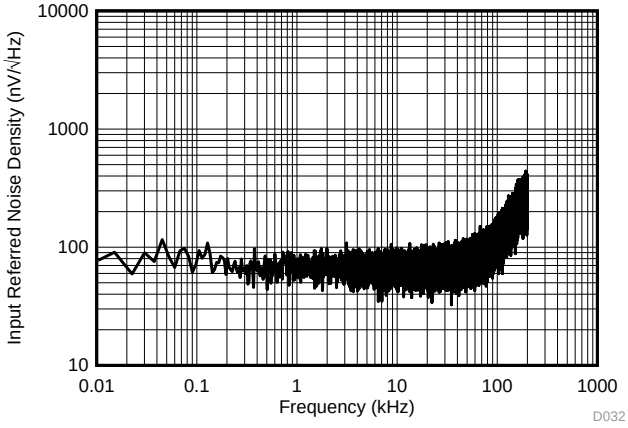
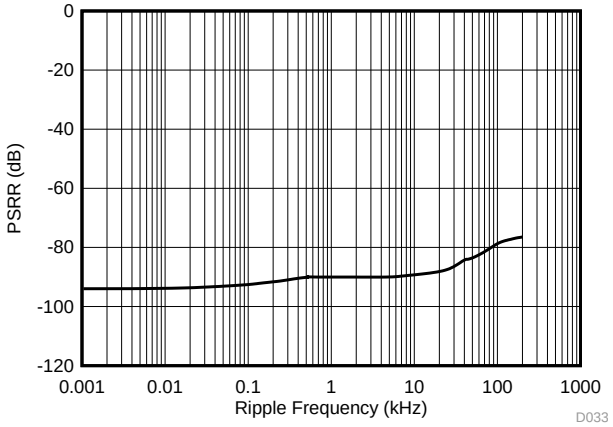


Figure 33. Input-Referred Noise Density vs Frequency

Copyright © 2016–2018, Texas Instruments Incorporated

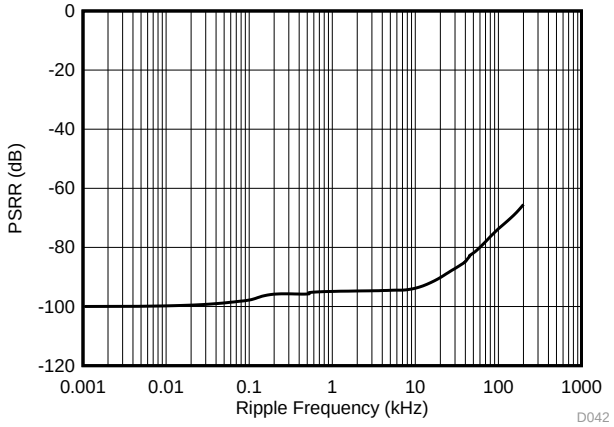
Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, VINP = –250 mV to 250 mV, VINN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



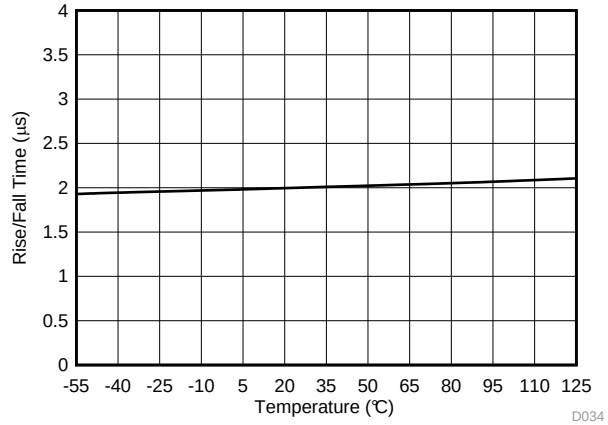
vs VDD1

Figure 34. Power-Supply Rejection Ratio vs Ripple Frequency



vs VDD2

Figure 35. Power-Supply Rejection Ratio vs Ripple Frequency



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 36. Output Rise and Fall Time vs Temperature

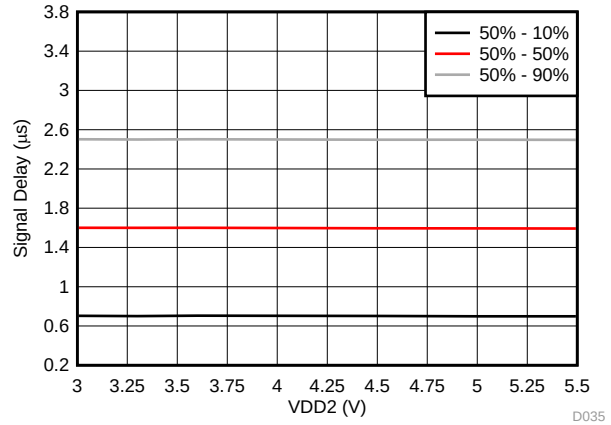
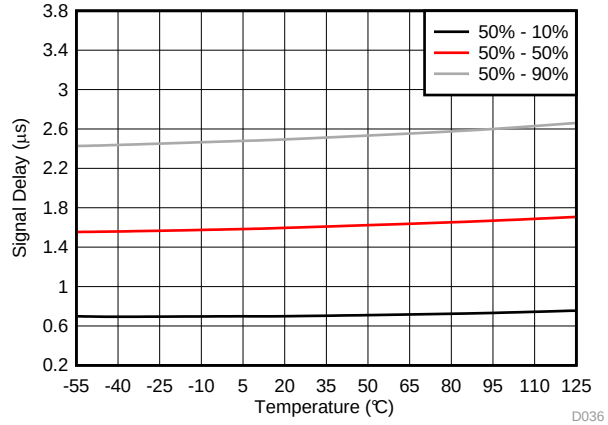


Figure 37. V_{IN} to V_{OUT} Signal Delay vs Low-Side Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 38. V_{IN} to V_{OUT} Signal Delay vs Temperature

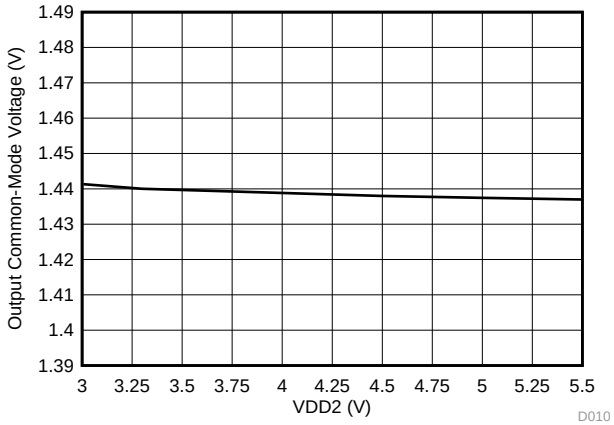
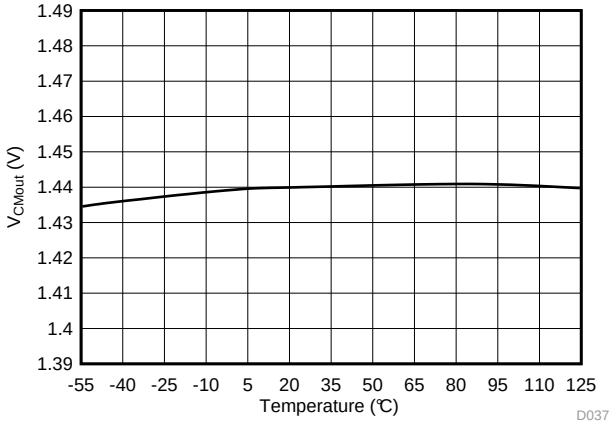


Figure 39. Output Common-Mode Voltage vs Low-Side Supply Voltage

Copyright © 2016–2018, Texas Instruments Incorporated

Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, VINP = –250 mV to 250 mV, VINN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 40. Output Common-Mode Voltage vs Temperature

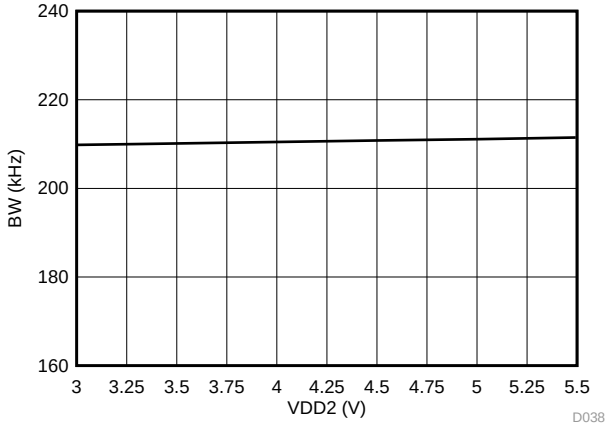
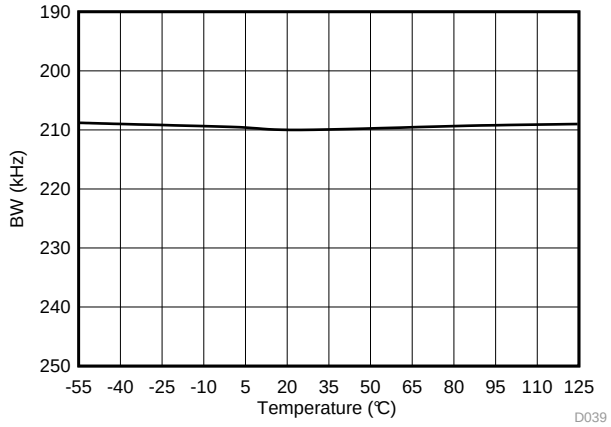


Figure 41. Output Bandwidth vs Low-Side Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 42. Output Bandwidth vs Temperature

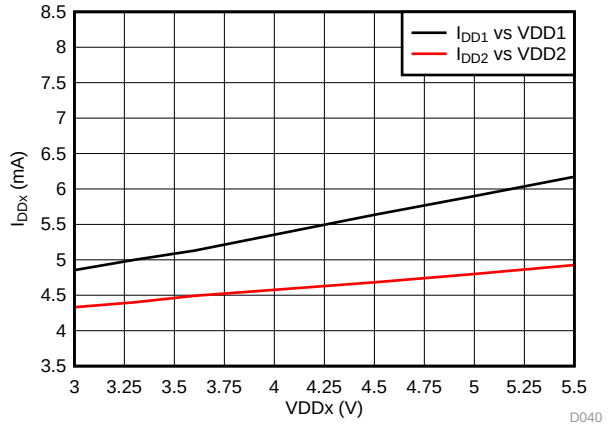
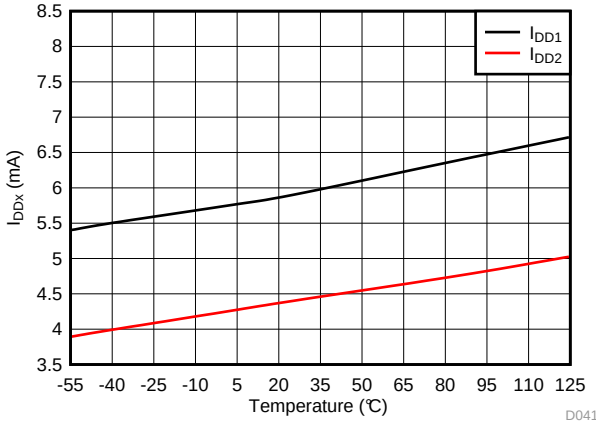


Figure 43. Supply Current vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 44. Supply Current vs Temperature

Copyright © 2016–2018, Texas Instruments Incorporated

8 Parameter Measurement Information

8.1 Timing Diagrams

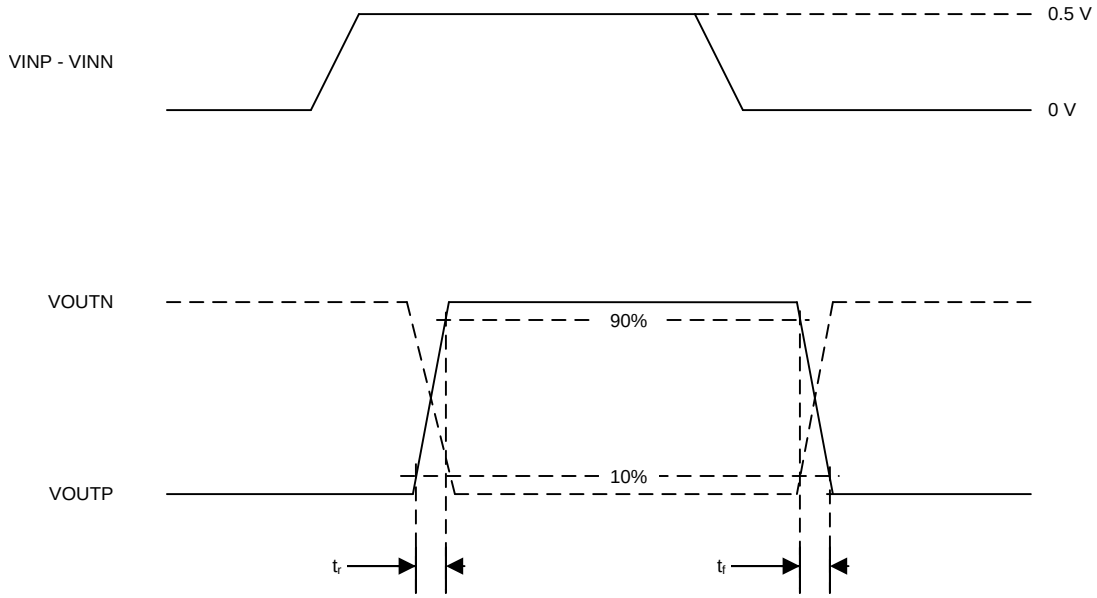


Figure 45. Rise and Fall Time Test Waveforms

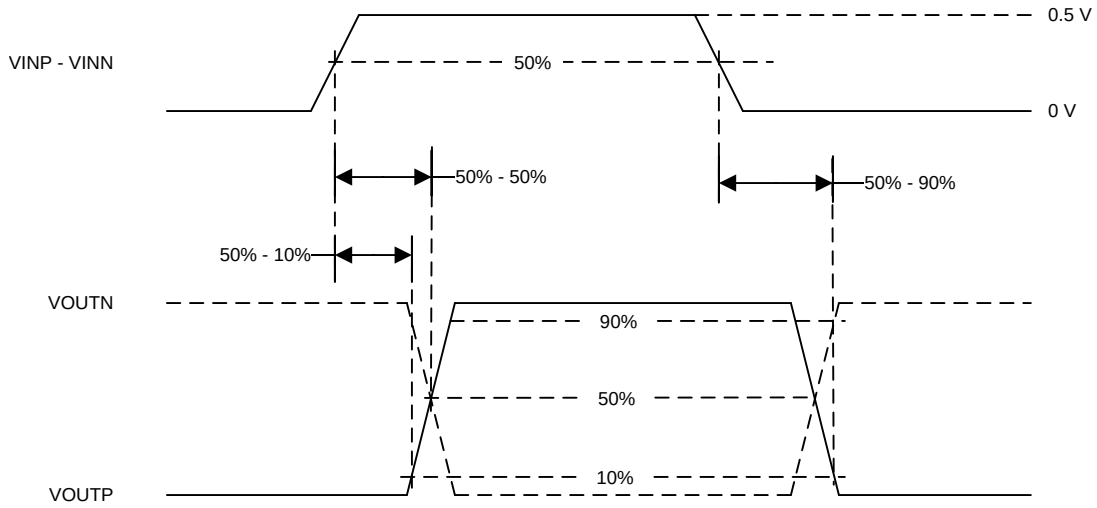


Figure 46. Delay Time Test Waveforms

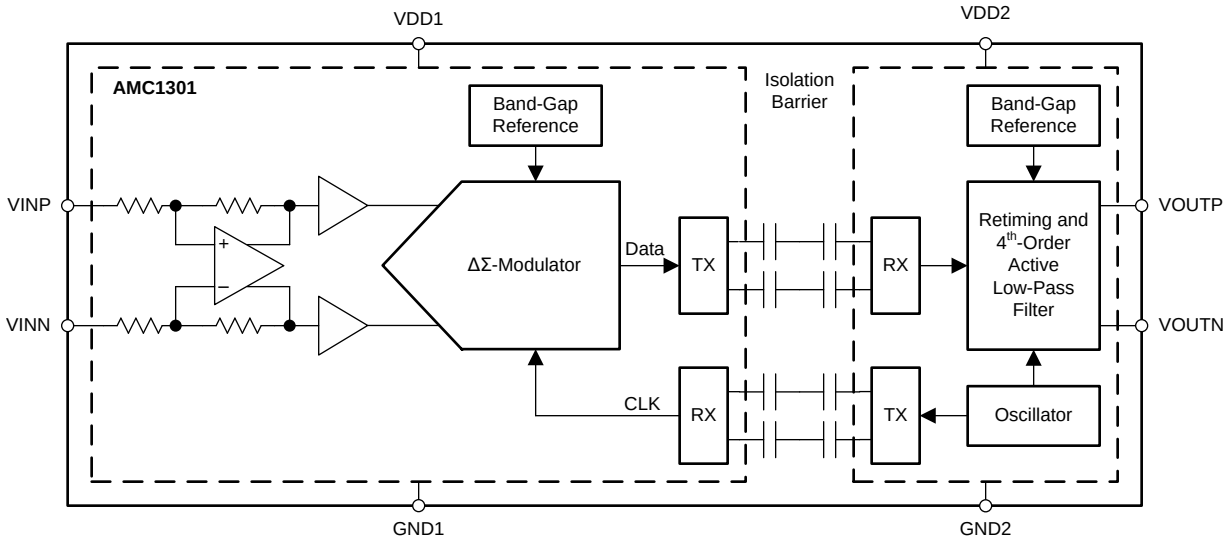
9 Detailed Description

9.1 Overview

The AMC1301 is a fully-differential, precision, isolated amplifier. The input stage of the device consists of a fully-differential amplifier that drives a second-order, delta-sigma (ΔΣ) modulator. The modulator uses the internal voltage reference and clock generator to convert the analog input signal to a digital bitstream. The drivers (called *TX* in the *Functional Block Diagram*) transfer the output of the modulator across the isolation barrier that separates the high-side and low-side voltage domains. The received bitstream and clock are synchronized and processed by a fourth-order analog filter on the low-side and presented as a differential output of the device, as shown in the *Functional Block Diagram*.

The SiO_2-based, double-capacitive isolation barrier supports a high level of magnetic field immunity, as described in *ISO72x Digital Isolator Magnetic-Field Immunity*. The digital modulation used in the AMC1301 and the isolation barrier characteristics result in high reliability and common-mode transient immunity.

9.2 Functional Block Diagram



9.3 Feature Description

9.3.1 Analog Input

The AMC1301 incorporates front-end circuitry that contains a fully-differential amplifier followed by a ΔΣ modulator sampling stage. The gain of the differential amplifier is set by internal precision resistors to a factor of 4 with a differential input impedance of 22 kΩ. Consider the input impedance of the AMC1301 in designs with high-impedance signal sources that may cause degradation of gain and offset specifications. The importance of this effect, however, depends on the desired system performance.

Additionally, the input bias current caused by the internal common-mode voltage at the output of the differential amplifier causes an offset that is dependent on the actual amplitude of the input signal. See the *Isolated Voltage Sensing* section for more details on reducing this effect.

There are two restrictions on the analog input signals (VINP and VINN). First, if the input voltage exceeds the range GND1 – 6 V to VDD1 + 0.5 V, then the input current must be limited to 10 mA because the device input electrostatic discharge (ESD) protection turns on. In addition, the linearity and noise performance of the device are ensured only when the analog input voltage remains within the specified linear full-scale range (FSR) and within the specified common-mode input voltage range.

Copyright © 2016–2018, Texas Instruments Incorporated

Feature Description (continued)

9.3.2 Fail-Safe Output

The AMC1301 offers a fail-safe output that simplifies diagnostics on system level. The fail-safe output is active in two cases:

- When the high-side supply VDD1 of the AMC1301 is missing, or
- When the common-mode input voltage, that is V_{CM} = (VINP + VINN) / 2, exceeds the minimum common-mode over-voltage detection level V_{CMov} of VDD1 – 2 V.

The fail-safe output of the AMC1301 is a negative differential output voltage value that differs from the negative clipping output voltage, as shown in Figure 47 and Figure 48. As a reference value for the fail-safe detection on a system level, use the $V_{FAILSAFE}$ maximum value of –2.545 V.

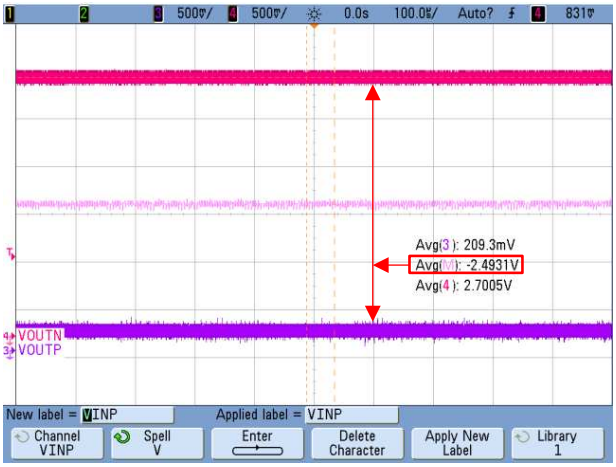


Figure 47. Typical Negative Clipping Output of the AMC1301

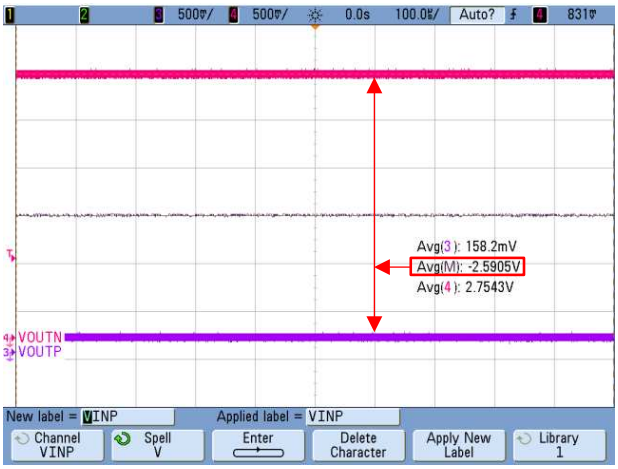


Figure 48. Typical Failsafe Output of the AMC1301

9.4 Device Functional Modes

The AMC1301 is operational when the power supplies VDD1 and VDD2 are applied, as specified in *Recommended Operating Conditions*.

Copyright © 2016–2018, Texas Instruments Incorporated

10 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

10.1 Application Information

The AMC1301 offers unique linearity, high input common-mode and power-supply rejection, low ac and dc errors, and low temperature drift. These features make the AMC1301 a robust, high-performance, isolated amplifier for industrial applications where high voltage isolation is required.

10.2 Typical Applications

10.2.1 Frequency Inverter Application

Isolated amplifiers are widely used in frequency inverters that are critical parts of industrial motor drives, photovoltaic inverters, uninterruptible power supplies, electrical and hybrid electrical vehicles, and other industrial applications. The input structure of the AMC1301 is optimized for use with low-value shunt resistors and is therefore tailored for isolated current sensing using shunts.

Figure 49 shows a typical operation of the AMC1301 for current sensing in a frequency inverter application. Phase current measurement is done through the shunt resistor, R_{SHUNT} (in this case, a two-pin shunt). The differential input and the high common-mode transient immunity of the AMC1301 ensure reliable and accurate operation even in high-noise environments (such as the power stage of the motor drive).

Additionally, the AMC1301 may also be used for isolated voltage measurement of the dc-link, as described in the *Isolated Voltage Sensing* section.

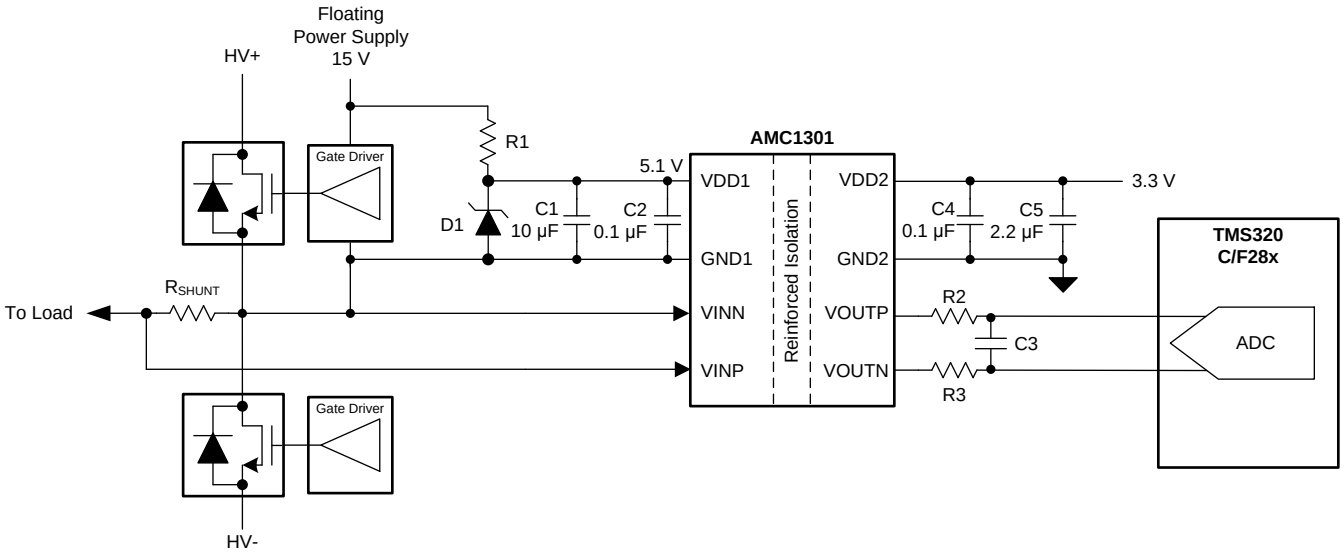


Figure 49. Using the AMC1301 for Current Sensing in Frequency Inverters

Copyright © 2016–2018, Texas Instruments Incorporated

Typical Applications (continued)

10.2.1.1 Design Requirements

Table 1 lists the parameters for the typical application in Figure 49.

Table 1. Design Requirements

PARAMETER	VALUE
High-side supply voltage	3.3 V or 5 V
Low-side supply voltage	3.3 V or 5 V
Voltage drop across the shunt for a linear response	± 250 mV (maximum)

10.2.1.2 Detailed Design Procedure

The high-side power supply (VDD1) for the AMC1301 is derived from the power supply of the upper gate driver. Further details are provided in the *Power Supply Recommendations* section.

The floating ground reference (GND1) is derived from one of the ends of the shunt resistor that is connected to the negative input of the AMC1301 (VINN). If a four-pin shunt is used, the inputs of the AMC1301 are connected to the inner leads and GND1 is connected to one of the outer shunt leads.

Use Ohm's Law to calculate the voltage drop across the shunt resistor (V_{SHUNT}) for the desired measured current: $V_{SHUNT} = I \times R_{SHUNT}$.

Consider the following two restrictions to choose the proper value of the shunt resistor R_{SHUNT}:

- The voltage drop caused by the nominal current range must not exceed the recommended differential input voltage range: $V_{SHUNT} \leq \pm 250$ mV
- The voltage drop caused by the maximum allowed overcurrentmust not exceed the input voltage that causes a clipping output: $V_{SHUNT} \leq V_{Clipping}$

For best performance, use an RC filter (components R_2, R_3, and C_3 in Figure 49) to minimize the noise of the differential output signal. Tailor the bandwidth of this RC filter to the bandwidth requirement of the system. TI recommends an NP0-type capacitor to be used for C_3.

For more information on the general procedure to design the filtering and driving stages of SAR ADCs, consult the TI Precision Designs *18-Bit, 1MSPS Data Acquisition Block (DAQ) Optimized for Lowest Distortion and Noise* and *18-Bit Data Acquisition Block (DAQ) Optimized for Lowest Power*, available for download at www.ti.com.

Copyright © 2016–2018, Texas Instruments Incorporated

10.2.1.3 Application Curves

In frequency inverter applications, the power switches must be protected in case of an overcurrent condition. To allow for fast powering off of the system, a low delay caused by the isolated amplifier is required. Figure 50 shows the typical full-scale step response of the AMC1301. Consider the delay of the required window comparator and the MCU to calculate the overall response time of the system.



Figure 50. Step Response of the AMC1301

The high linearity and low temperature drift of offset and gain errors of the AMC1301, as shown in Figure 51, allows design of motor drives with low torque ripple.

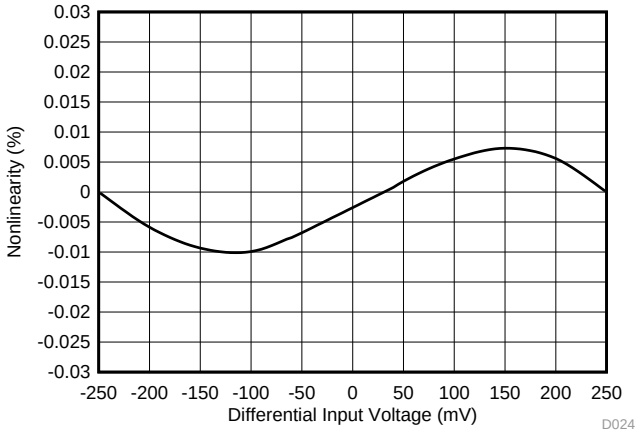


Figure 51. Typical Nonlinearity of the AMC1301

Copyright © 2016–2018, Texas Instruments Incorporated

10.2.2 Isolated Voltage Sensing

The AMC1301 is optimized for usage in current-sensing applications using low-impedance shunts. However, the device may also be used in isolated voltage-sensing applications if the effect of the (usually higher) impedance of the resistor divider used in this case is considered.

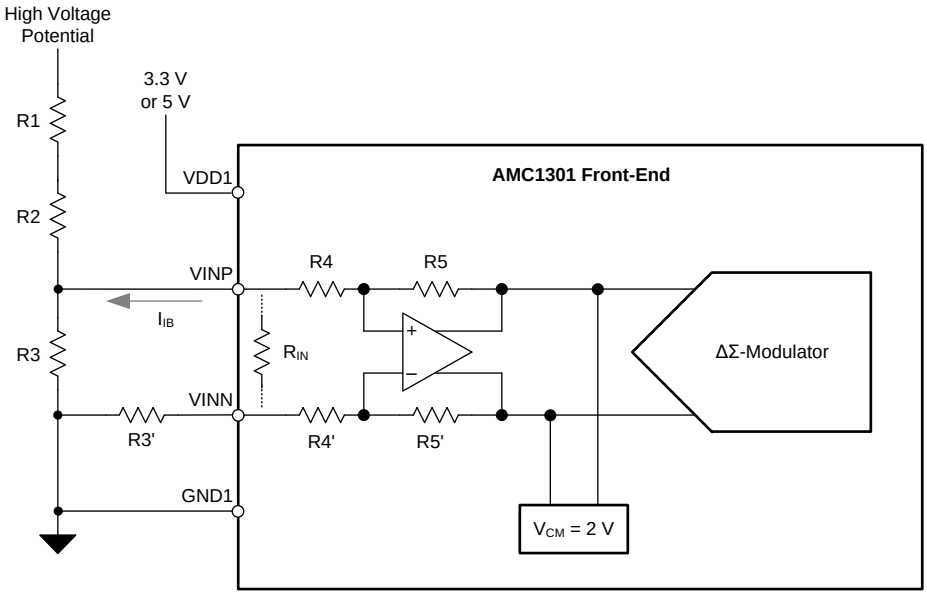


Figure 52. Using the AMC1301 for Isolated Voltage Sensing

10.2.2.1 Design Requirements

Figure 52 shows a simplified circuit typically used in high-voltage sensing applications. The high-impedance resistors (R1 and R2) dominate the current value that flows through the resistive divider. The resistance of the sensing resistor R3 is chosen to meet the input voltage range of the AMC1301. This resistor and the input impedance of the device (R_{IN} = 18 kΩ) also create a voltage divider that results in an additional gain error. With the assumption of R1 and R2 having a considerably higher value than R3 and omitting R3' for the moment, the resulting total gain error is estimated using Equation 1, with E_G being the initial gain error of the AMC1301.

$$\left|E_{Gtot}\right| = \left|E_G\right| + \frac{R_3}{R_{IN}} \tag{1}$$

This gain error may be easily minimized during the initial system-level gain calibration procedure.

10.2.2.2 Detailed Design Procedure

As indicated in Figure 52, the output of the integrated differential amplifier is internally biased to a common-mode voltage of 2 V. This voltage results in a bias current I_{IB} through the resistive network R4 and R5 (or R4' and R5') used for setting the gain of the amplifier. The value of this current is specified in the *Pin Configuration and Functions* section. This bias current generates additional offset and gain errors that depend on the value of the resistor R3. Because the value of this bias current depends on the actual common-mode amplitude of the input signal (as shown in Figure 53), the initial system offset calibration eliminates the offset but not the gain error component. Therefore, in systems with high accuracy requirements, a series resistor is recommended to be used at the negative input (VINN) of the AMC1301 with a value equal to the shunt resistor R3 (that is, R3' = R3 in Figure 52) to eliminate the effect of the bias current.

This additional series resistor (R3') influences the gain error of the circuit. The effect is calculated using Equation 2 with R4 = R4' = 12.5 kΩ. The effect of the internal resistors R5 = R5' cancels in this calculation.

$$E_G(\%) = \left(1 - \frac{R4}{R4'+R3'}\right) * 100\% \tag{2}$$

Copyright © 2016–2018, Texas Instruments Incorporated

10.2.2.3 Application Curve

Figure 53 shows the dependency of the input bias current on the common-mode voltage at the input of the AMC1301.

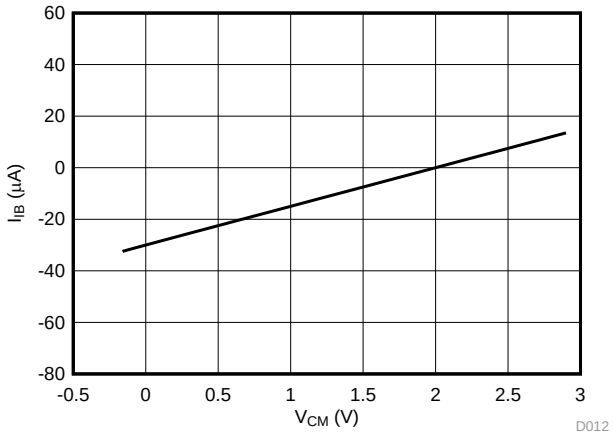


Figure 53. Input Current vs Input Common-Mode Voltage

10.3 Do's and Don'ts

Do not leave the inputs of the AMC1301 unconnected (floating) when the device is powered up. If both device inputs are left floating, the input bias current drives them to the output common-mode of the analog front-end of approximately 2 V. If the high-side supply voltage VDD1 is below 4 V, the internal common-mode overvoltage detector turns on and the output functions as described in the *Fail-Safe Output* section, which may lead to an undesired reaction on the system level.

Copyright © 2016–2018, Texas Instruments Incorporated

11 Power Supply Recommendations

In a typical frequency inverter application, the high-side power supply (VDD1) for the device is derived from the floating power supply of the upper gate driver. For lowest cost, a Zener diode may be used to limit the voltage to 5 V (or 3.3 V, depending on the design) ± 10%. Alternatively a low-cost, low-dropout (LDO) regulator (for example, the LM317-N) may be used to minimize noise on the power supply. TI recommends a low-ESR decoupling capacitor of 0.1 µF to filter this power-supply path. Place this capacitor (C_2 in Figure 54) as close as possible to the VDD1 pin of the AMC1301 for best performance. If better filtering is required, an additional 10-µF capacitor may be used. The floating ground reference (GND1) is derived from the end of the shunt resistor, which is connected to the negative input (VINN) of the device. If a four-pin shunt is used, the device inputs are connected to the inner leads, and GND1 is connected to one of the outer leads of the shunt.

To decouple the digital power supply on the controller side, use a 0.1-µF capacitor placed as close to the VDD2 pin of the AMC1301 as possible, followed by an additional capacitor from 1 µF to 10 µF.

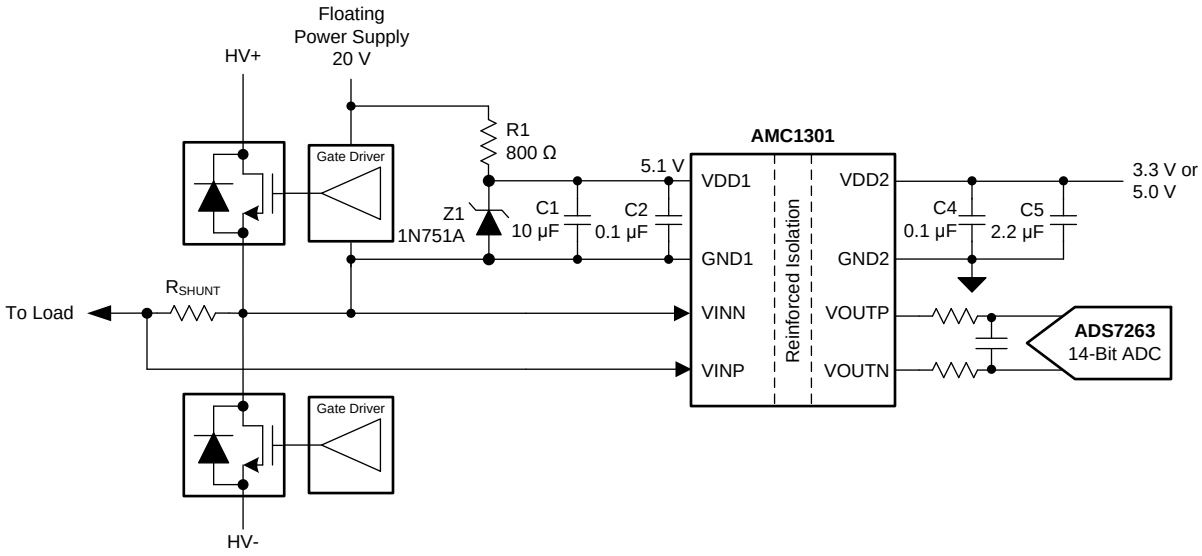


Figure 54. Zener-Diode-Based, High-Side Power Supply

12 Layout

12.1 Layout Guidelines

A layout recommendation showing the critical placement of the decoupling capacitors (as close as possible to the AMC1301) and placement of the other components required by the device is shown in Figure 55. For best performance, place the shunt resistor close to the VINP and VINN inputs of the AMC1301 and keep the layout of both connections symmetrical.

12.2 Layout Example

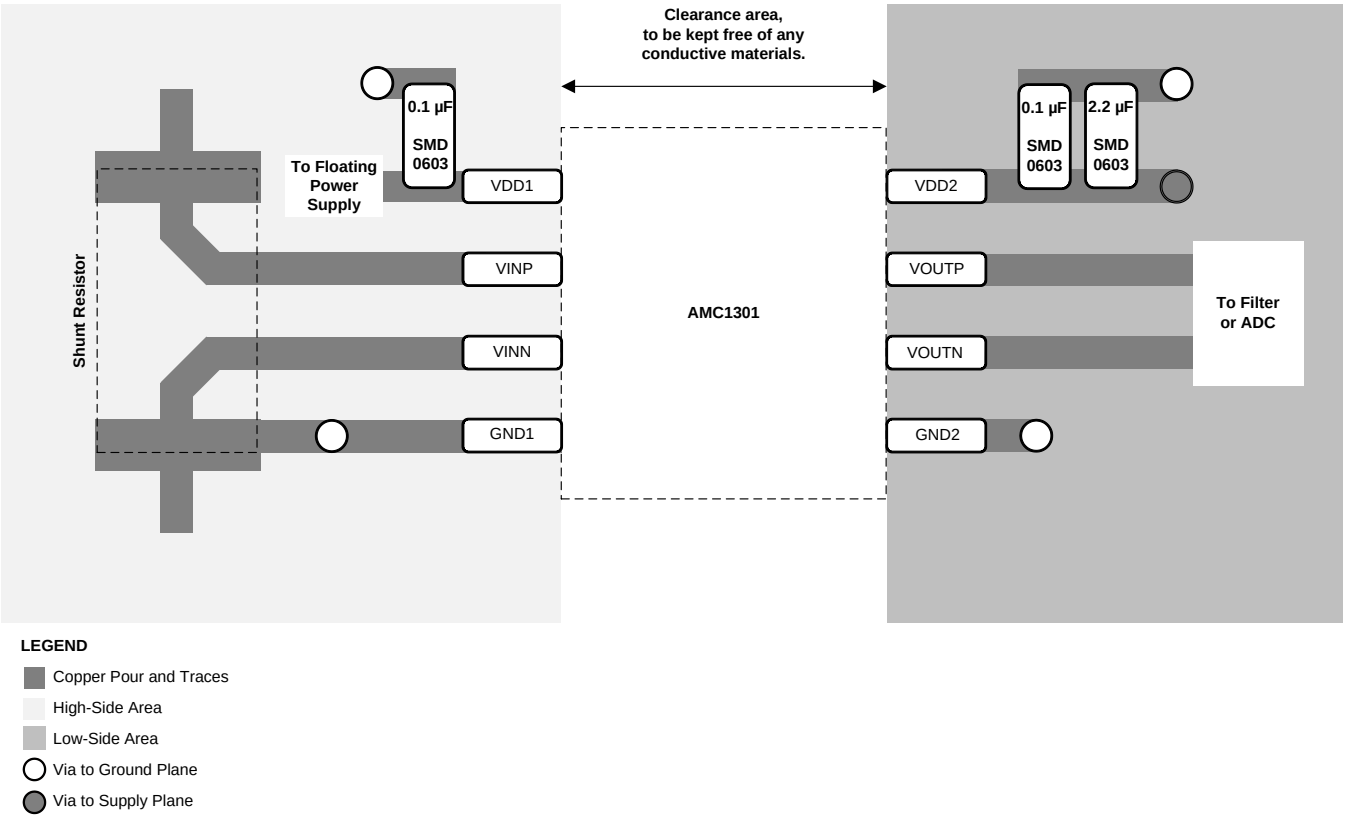


Figure 55. Recommended Layout of the AMC1301

Copyright © 2016–2018, Texas Instruments Incorporated

13 Device and Documentation Support

13.1 Documentation Support

13.1.1 Related Documentation

For related documentation, see the following:

- *Isolation Glossary*
- *Dual, 1MSPS, 16-/14-/12-Bit, 4×2 or 2×2 Channel, Simultaneous Sampling Analog-to-Digital Converter*
- *LM117, LM317-N Wide Temperature Three-Pin Adjustable Regulator*
- *ISO72x Digital Isolator Magnetic-Field Immunity*
- *18-Bit, 1-MSPS Data Acquisition Block (DAQ) Optimized for Lowest Distortion and Noise*
- *18-Bit, 1-MSPS Data Acquisition Block (DAQ) Optimized for Lowest Power*

13.2 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to order now.

Table 2. Related Links

PARTS	PRODUCT FOLDER	ORDER NOW	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
AMC1301	Click here	Click here	Click here	Click here	Click here
AMC1301S	Click here	Click here	Click here	Click here	Click here

13.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

13.4 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community ***TI's Engineer-to-Engineer (E2E) Community.*** Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support ***TI's Design Support*** Quickly find helpful E2E forums along with design support tools and contact information for technical support.

13.5 Trademarks

E2E is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

13.6 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

13.7 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

Copyright © 2016–2018, Texas Instruments Incorporated

14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Copyright © 2016–2018, Texas Instruments Incorporated

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
AMC1301DWV	ACTIVE	SOIC	DWV	8	64	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 125	AMC1301	Samples
AMC1301DWVR	ACTIVE	SOIC	DWV	8	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 125	AMC1301	Samples
AMC1301SDWV	ACTIVE	SOIC	DWV	8	64	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-55 to 125	AMC1301S	Samples
AMC1301SDWVR	ACTIVE	SOIC	DWV	8	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-55 to 125	AMC1301S	Samples

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and

continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF AMC1301 :

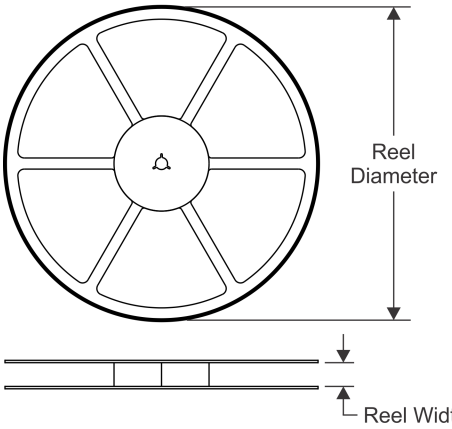
- Automotive: AMC1301-Q1

NOTE: Qualified Version Definitions:

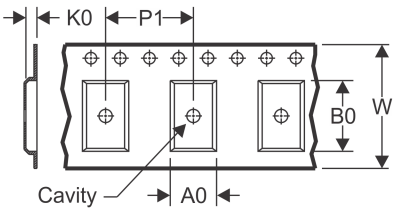
- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

TAPE AND REEL INFORMATION

REEL DIMENSIONS

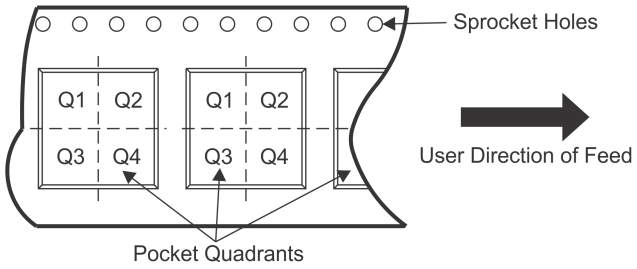


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

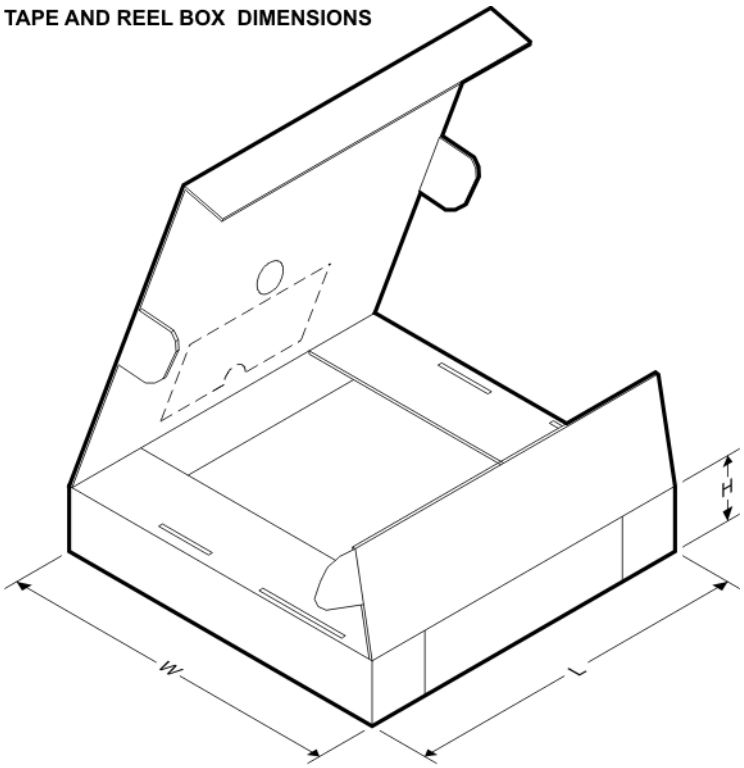
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

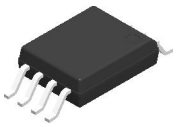
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
AMC1301DWVR	SOIC	DWV	8	1000	330.0	16.4	12.05	6.15	3.3	16.0	16.0	Q1
AMC1301SDWVR	SOIC	DWV	8	1000	330.0	16.4	12.05	6.15	3.3	16.0	16.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

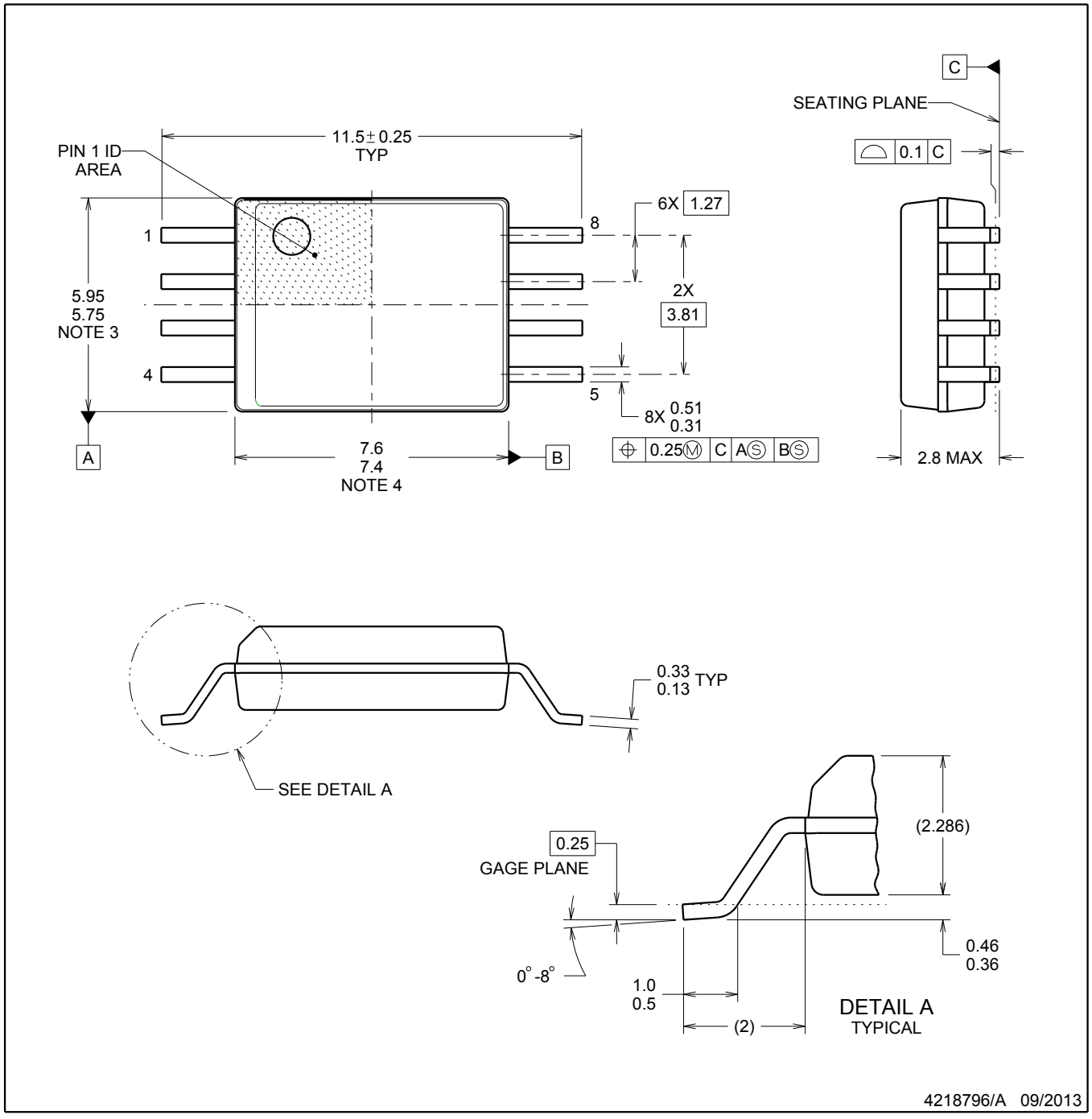
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
AMC1301DWVR	SOIC	DWV	8	1000	350.0	350.0	43.0
AMC1301SDWVR	SOIC	DWV	8	1000	350.0	350.0	43.0



DWV0008A

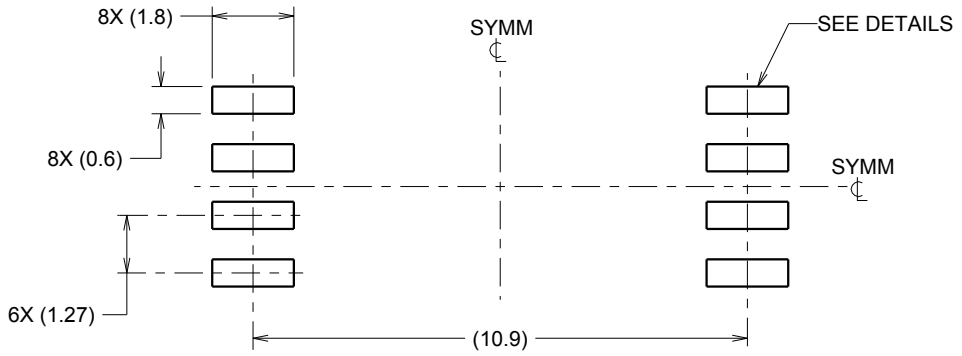
SOIC - 2.8 mm max height

SOIC

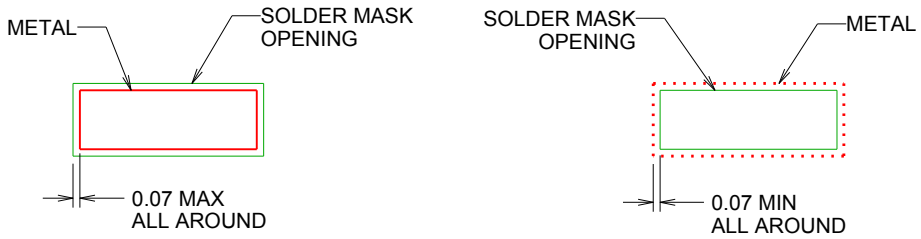


NOTES:

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm, per side.



LAND PATTERN EXAMPLE
9.1 mm NOMINAL CLEARANCE/CREEPAGE
SCALE:6X



SOLDER MASK DETAILS

4218796/A 09/2013

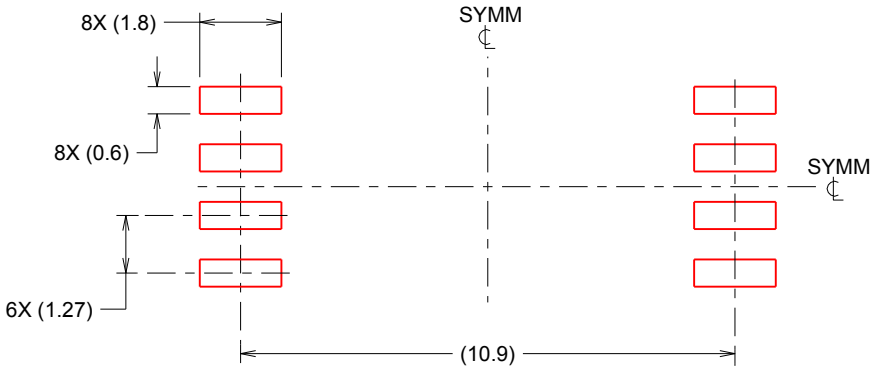
NOTES: (continued)

5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

DWV0008A

SOIC - 2.8 mm max height

SOIC



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:6X

4218796/A 09/2013

NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
8. Board assembly site may have different recommendations for stencil design.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES “AS IS” AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI’s products are provided subject to TI’s Terms of Sale (www.ti.com/legal/termsofsale.html) or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI’s provision of these resources does not expand or otherwise alter TI’s applicable warranties or warranty disclaimers for TI products.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2019, Texas Instruments Incorporated