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#### **DESCRIPTION**

The MAX485 is a half-duplex transceiver that meets the specifications of RS-485 and RS-422. Its BiCMOS design allows low power operation without sacrificing performance. The MAX485 meets the requirements of the RS-485 and RS-422 protocols up to 5Mbps underload. The ESD tolerance is more than  $\pm 8kV$  for both Human Body Model and  $\pm 15kV$  for IEC61000-4-2 Air Discharge Method on this device.

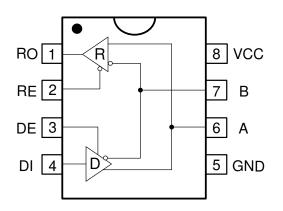
#### **FEATURES**

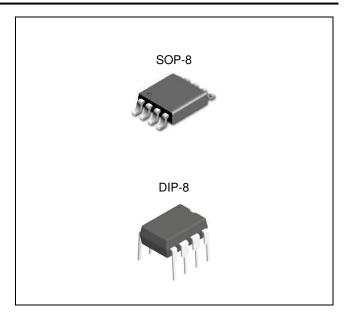
- Single +5V Supply
- Low Power BiCMOS
- Driver/Receiver Enable for Multi-Drop Configurations
- Half-Duplex Versions Available
- · Data rate: 5 Mbps
- ESD Specifications
  - ±15kV IEC61000-4-2 Air Discharge
  - ±8kV Human Body Model

#### **APPLICATIONS**

- Low Power RS-485 Systems
- DTE-DCE Interface
- · Packet Switching
- Local Area Networks
- Data Concentration
- Data Multiplexers
- Integrated Services Digital Network (ISDN)

#### PIN CONFIGRUATION AND LOGIC DIAGRAM





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| RUTH TABLE |          |      |        |            |    |         |  |   |  |
|------------|----------|------|--------|------------|----|---------|--|---|--|
|            | Т        | rans | missio | n          |    |         |  |   |  |
|            | Inputs   |      |        | Outputs    |    |         |  |   |  |
| RE         | DE       |      | DI     | Α          |    | В       |  |   |  |
| X          | 1        |      | 1      | 1          |    | 0       |  |   |  |
| Х          | 1        |      | 0      | 0          |    | 1       |  |   |  |
| 0          | 0        | Х    |        | Z          |    | Z       |  |   |  |
| 1          | 0        | Х    |        | Z          |    | Z       |  |   |  |
|            | Receiver |      |        |            |    |         |  |   |  |
|            | Inputs   |      |        |            |    | Outputs |  |   |  |
| RE         | DE       | А    |        | <b>\-В</b> | RO |         |  |   |  |
| 0          | 0        | ≥ +  |        | ≥ +0.2V    |    | 1       |  |   |  |
| 0          | 0        | 0    |        | ≤ -0.2V    |    | ≤ -0.2V |  | 0 |  |

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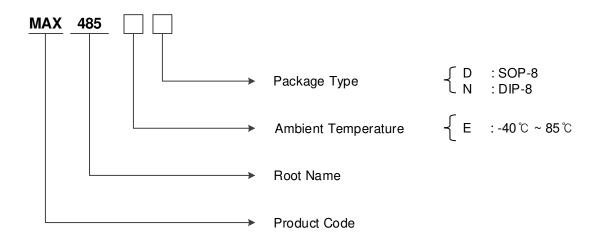
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### **ORDERING INFORMATION**

| Package | Oder No. | Description                | Marking | Compliance  | Status     |
|---------|----------|----------------------------|---------|-------------|------------|
| SOP-8   | MAX485ED | RS-485/RS-422 Transceivers | MAX485E | RoHS, Green | Active     |
| DIP-8   | MAX485EN | RS-485/RS-422 Transceivers | MAX485E | RoHS, Green | Contact us |



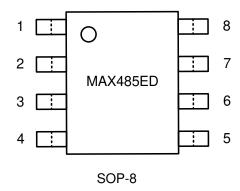
### **ABSOLUTE MAXIMUM RATINGS**

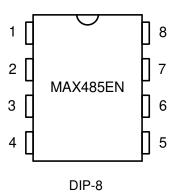
| Characteristic            | Symbol                            | Min  | Max       | Unit |
|---------------------------|-----------------------------------|------|-----------|------|
| Supply Voltage            | Vcc                               |      | 7         | V    |
| Control Input Voltage     | V <sub>DE</sub> , V <sub>RE</sub> | -0.3 | Vcc + 0.5 | V    |
| Driver Input Voltage      | V <sub>DI</sub>                   | -0.3 | Vcc + 0.5 | V    |
| Driver Output Voltage     | A, B                              | -15  | 15        | V    |
| Receiver Input Voltage    | A, B                              | -15  | 15        | V    |
| Receiver Output Voltage   | V <sub>RO</sub>                   | -0.3 | Vcc + 0.5 | V    |
| Junction Temperature      | TJ                                | -40  | 125       | °C   |
| Storage Temperature Range | T <sub>STG</sub>                  | -65  | 150       | °C   |

#### **RECOMMENDED OPERATING CONDITIONS**

| Characteristic                       | Symbol         | Min  | Max  | Unit |
|--------------------------------------|----------------|------|------|------|
| Supply Voltage                       | Vcc            | 4.75 | 5.25 | V    |
| Operating Ambient Temperature Ranges | T <sub>A</sub> | -40  | 85   | °C   |

### **PIN CONFIGURATION**





#### **PIN DESCRIPTION**

| Pin No.  | SOP-8 / DIP-8 PKG |  |  |  |  |
|----------|-------------------|--|--|--|--|
| Pili NO. | Name              | Function                                       |  |  |  |
| 1        | RO                | Receiver Output                                |  |  |  |
| 2        | RE*               | Receiver Output Enable Active Low              |  |  |  |
| 3        | DE                | Driver Output Enable Active High               |  |  |  |
| 4        | DI                | Driver Input                                   |  |  |  |
| 5        | GND               | Ground   |  |  |  |
| 6        | Α                 | Non-inverting Driver Output and Receiver Input |  |  |  |
| 7        | В                 | Inverting Driver Output and Receiver Input     |  |  |  |
| 8        | V <sub>CC</sub>   | Power Supply: 4.75V to 5.25V                   |  |  |  |

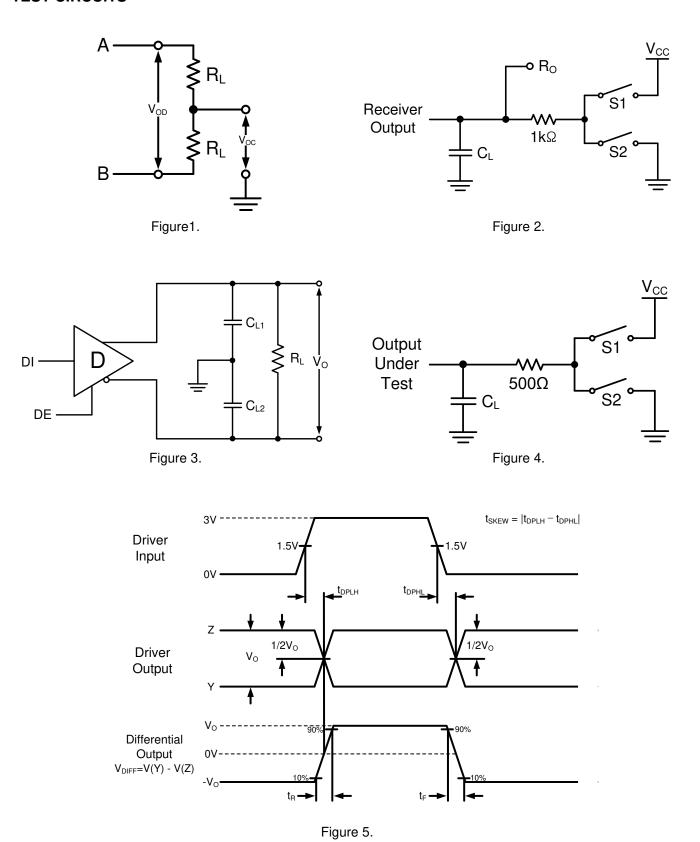
#### **ELECTRICAL CHARACTERISTICS**

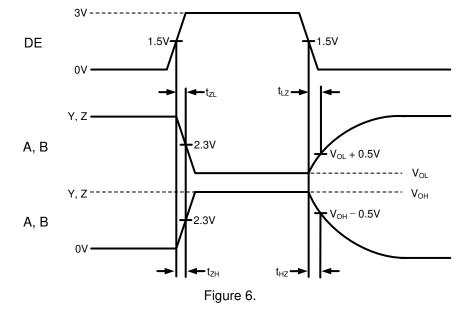
Unless otherwise specified:  $V_{CC} = 5V \pm 5\%$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ 

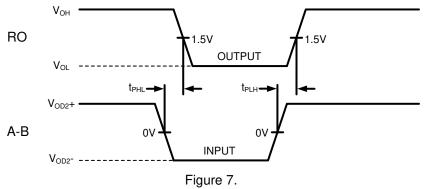
| PARAMETER                           | Symbol                          | CONDITIONS                                      |                       | MIN  | TYP | MAX  | UNITS |
|-------------------------------------|---------------------------------|---|-----------------------|------|-----|------|-------|
| DRIVER DC Characteristics           | L                               |   |                       |      |     | L    | L     |
| Differential Driver Output          | V <sub>OD1</sub>                | D Figure 1                                      |                       | GND  |     | Vcc  | V     |
| (no load)                           | V OD1                           | R <sub>L</sub> = ∞, Figure 1                    |                       | GND  |     | VCC  | V     |
| Differential Driver Output          | V <sub>OD2</sub>                | $R_L = 50\Omega \text{ (RS-422)},$              | Figure 1              | 2    |     | Vcc  | V     |
| (with load)                         | V OD2                           | $R_L = 27\Omega \text{ (RS-485)},$              | Figure 1              | 1.5  |     | Vcc  | V     |
| Change in Magnitude of Driver       |                                 |   |                       |      |     |      |       |
| Differential Output Voltage for     | $\Delta V_{\text{OD}}$          | $R_L = 27\Omega$ or $50\Omega$ , Fig            | gure 1                |      |     | 0.2  | V     |
| Complementary Output States         |                                 |   |                       |      |     |      |       |
| Driver Common-Mode Output Voltage   | Voc                             | $R_L = 27\Omega$ or $50\Omega$ , Fig            | gure 1                |      |     | 3    | V     |
| Change in Magnitude of Driver       |                                 |   |                       |      |     |      |       |
| Common-Mode Output Voltage for      | ΔVoc                            | $R = 27\Omega$ or $50\Omega$ , Figure 1         | ure 1                 |      |     | 0.2  | V     |
| Complementary Output States         |                                 |   |                       |      |     |      |       |
| Input High Voltage                  | V <sub>IH</sub>                 | DE, DI, RE*                                     |                       | 2.0  |     |      | V     |
| Input Low Voltage                   | VIL                             | DE, DI, RE*                                     |                       |      |     | 0.8  | V     |
| Input Current                       | I <sub>IN1</sub>                | DE, DI, RE*                                     |                       |      |     | ±10  | uA    |
| <b>Driver Short Circuit Current</b> |                                 |   |                       |      |     |      |       |
| Driver Short-Circuit Current,       | loon.                           | -7V ≤ V <sub>O</sub> ≤ 12V                      |                       |      |     | ±250 | mA    |
| Vo = High                           | losd1                           | -7 V S VO S 12 V                                |                       |      |     | ±230 | IIIA  |
| Driver Short-Circuit Current,       | 1                               | 7)/ 5)/ 540)/                                   |                       |      |     | ±250 | mA    |
| V <sub>O</sub> = Low                | I <sub>OSD2</sub>               | -7V ≤ V <sub>O</sub> ≤ 12V                      |                       |      |     | 1230 | IIIA  |
| DRIVER AC Characteristics           |                                 |   |                       |      |     |      |       |
| Max. Transmission Rate              | f <sub>MAX</sub>                |   |                       | 5    |     |      | Mbps  |
| Driver Input to Output              | toplh                           |   |                       |      | 30  | 60   | ns    |
| Driver input to Output              | tophl                           | Figure 3 & 5                                    |                       |      | 30  | 60   | ns    |
| Driver Output Skew to Output        | tskew                           | $R_L = 54\Omega, C_{L1} = C_{L2}$               | = 100pF               |      | 5   | 10   | ns    |
| Driver Rise or Fall Time            | t <sub>r</sub> , t <sub>f</sub> |   |                       |      | 15  | 40   | ns    |
| Driver Enable to Output High        | tzн                             |   | S <sub>2</sub> closed |      | 40  | 70   | ns    |
| Driver Enable to Output Low         | tzL                             | Figure 4 & 6                                    | S <sub>1</sub> closed |      | 40  | 70   | ns    |
| Driver Disable Time from Low        | t <sub>HZ</sub>                 | C <sub>L</sub> =100pF                           | S <sub>2</sub> closed |      | 40  | 70   | ns    |
| Driver Disable Time from High       | tız                             |   | S <sub>1</sub> closed |      | 40  | 70   | ns    |
| RECEIVER DC Characteristics         |                                 |   |                       |      |     |      |       |
| Receiver Differential Threshold     | V <sub>TH</sub>                 | -7V ≤ V <sub>CM</sub> ≤ 12V                     |                       | -0.2 |     | 0.2  | V     |
| Voltage                             | VIH                             | -7 V Z V CM Z 12 V                              |                       | -0.2 |     | 0.2  | V     |
| Receiver Input Hysteresis           | $\Delta V_{TH}$                 | V <sub>CM</sub> = 0V                            |                       |      | 20  |      | mV    |
| Receiver Output High Voltage        | V <sub>OH</sub>                 | $I_{O} = -4mA, V_{ID} = +200mV$                 |                       | 3.5  |     |      | V     |
| Receiver Output Low Voltage         | V <sub>OL</sub>                 | I <sub>O</sub> = +4mA, V <sub>ID</sub> = -200mV |                       |      |     | 0.4  | V     |
| Three-State (High Impedance) Output | nce) Output                     |   | * 51/                 |      |     | 1.4  |       |
| Current at Receiver                 | lozr                            | $0.4V \le V_0 \le 2.4V, RE^* = 5V$              |                       |      |     | ±1   | uA    |
| Receiver Input Resistance           | R <sub>IN</sub>                 | -7V ≤ V <sub>CM</sub> ≤ 12V                     |                       | 12   | 15  |      | kΩ    |
| 1 10 1/A B                          |                                 | DE = 0V   | V <sub>IN</sub> = 12V |      |     | 1.0  |       |
| Input Current (A, B)                | I <sub>IN2</sub>                | Vcc = 0V or 5.25V                               | $V_{IN} = -7V$        |      |     | -0.8 | mA    |
| Receiver Short-Circuit Current      | Iosr                            | 0V ≤ V <sub>0</sub> ≤ V <sub>cc</sub>           |                       | 7    |     | 95   | mA    |

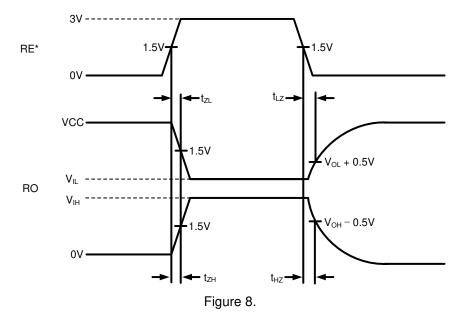
| RECEIVER AC Characteristics     |                  |                            |                                      |    |     |     |     |  |
|---------------------------------|------------------|----------------------------|--------------------------------------|----|-----|-----|-----|--|
| Possiver Input to Output        | tplh             | Figure 2 & 7               |                                      | 20 | 45  | 100 | ns  |  |
| Receiver Input to Output        | tphl             |                            |                                      | 20 | 45  | 100 | ns  |  |
| tPLH - tPHL   Differential      | tour             | C <sub>L</sub> = 15pF      | S <sub>1</sub> , S <sub>2</sub> open |    | 13  |     | ns  |  |
| Receiver Skew                   | t <sub>SKD</sub> | OL = 13pi                  |                                      |    | 13  |     | 115 |  |
| Receiver Enable to Output Low   | tzL              |                            | S <sub>1</sub> closed                |    | 45  | 70  | ns  |  |
| Receiver Enable to Output High  | tzн              | Figure 2 & 8               | S <sub>2</sub> closed                |    | 45  | 70  | ns  |  |
| Receiver Disable Time from Low  | t <sub>LZ</sub>  | C <sub>L</sub> = 15pF      | S <sub>1</sub> closed                |    | 45  | 70  | ns  |  |
| Receiver Disable Time from High | tнz              | S <sub>2</sub> close       |                                      |    | 45  | 70  | Ns  |  |
| Supply Current                  |                  |                            |                                      |    |     |     |     |  |
| No Load Cumply Current          |                  | RE = 0V or V <sub>CC</sub> | DE=Vcc                               |    | 900 |     |     |  |
| No-Load Supply Current          | Icc              |                            | DE=0V                                |    | 600 |     | uA  |  |

#### **TEST CIRCUITS**









#### APPLICATION INFORMATION

#### **FUNCTIONAL DESCRIPTION**

The MAX485 is half-duplex differential transceiver that meets the requirements of RS-485 and RS-422. The RS-485 standard is ideal for multi-drop applications and for long-distance interfaces. RS-485 allows up to 32 drivers and 32 receivers to be connected to a data bus, making it an ideal choice for multi-drop applications. Since the cabling can be as long as 4,000 feet, RS-485 transceivers are equipped with a wide (-7V to +12V) common mode range to accommodate ground potential differences. Because RS-485 is a differential interface, data is virtually immune to noise in the transmission line.

#### **DRIVERS**

The driver outputs of the MAX485 are differential outputs meeting the RS-485 and RS-422 standards. The typical voltage output swing with no load will be 0 Volts to +5 Volts. With worst case loading of  $54\Omega$  across the differential outputs, the drivers can maintain greater than 1.5V voltage levels. The drivers of the MAX485 have an enable control line which is active HIGH. A logic HIGH on DE (pin 3) will enable the differential driver outputs. A logic LOW on the DE(pin 3) will tri-state the driver output. The transmitters of the MAX485 will operate up to at least 5Mbps.

#### **RECEIVERS**

The MAX485 receiver has differential inputs with an input sensitivity as low as  $\pm 200 \text{mV}$ . Input impedance of the receivers is typically  $15 \text{k}\Omega$  ( $12 \text{k}\Omega$  minimum). A wide common mode range of -7V to +12V allows for large ground potential differences between systems. The receivers of the MAX485 have a tri-state enable control pin. A logic LOW on RE\* (pin 2) will enable the receiver, a logic HIGH on RE\*(pin 2) will disable the receiver. The receiver for the MAX485 will operate up to at least 5Mbps. The receiver is equipped with the fail-safe feature. Fail-safe guarantees that the receiver output will be in a HIGH state when the input is left unconnected.

# Low-Power, Slew-Rate-Limited RS-485/RS-422 Transceivers MAX485 REVISION NOTICE

The description in this datasheet can be revised without any notice to describe its electrical characteristics properly.