National Semiconductor

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LM391 Audio Power Driver

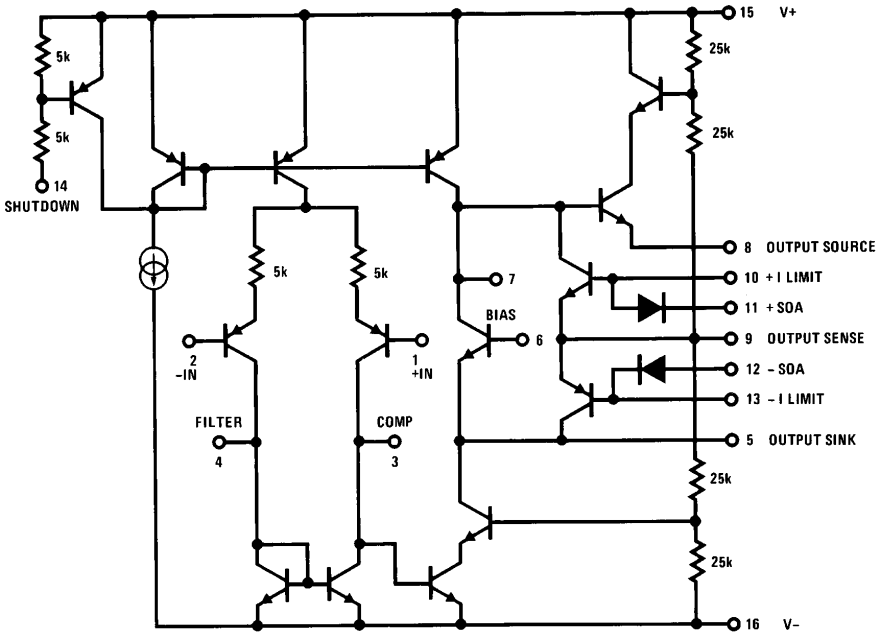
General Description

The LM391 audio power driver is designed to drive external power transistors in 10 to 100 watt power amplifier designs. High power supply voltage operation and true high fidelity performance distinguish this IC. The LM391 is internally protected for output faults and thermal overloads; circuitry providing output transistor protection is user programmable.

Features

- High Supply Voltage ±50V max
- Low Distortion 0.01%
- Low Input Noise 3 μV
- High Supply Rejection 90 dB
- Gain and Bandwidth Selectable
- Dual Slope SOA Protection
- Shutdown Pin

Equivalent Schematic and Connection Diagram



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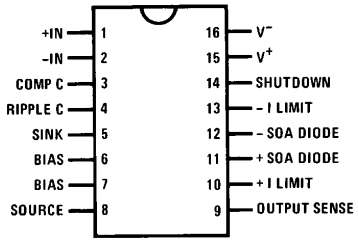
Dual-In-Line Package



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Top View

Order Number LM391N-100
See NS Package Number N16A

RRD-B30M115/Printed in U. S. A.

Absolute Maximum Ratings

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage	
LM391N-100	±50V or +100V
Input Voltage	Supply Voltage less 5V
Shutdown Current (Pin 14)	1 mA
Package Dissipation (Note 1)	1.39W
Storage Temperature	−65°C to +150°C
Operating Temperature	0°C to +70°C
Lead Temp. (Soldering, 10 sec.)	260°C
Thermal Resistance	
θ_{JC}	20°C/W
θ_{JA}	63°C/W

Electrical Characteristics $T_A = 25°C$ (The following are for $V^+ = 90\%\ V^+_{MAX}$ and $V^- = 90\%\ V^-_{MAX}$.)

Parameter	Conditions	Min	Typ	Max	Units
Quiescent Current LM391N-100	Current in Pin 15 $V_{IN} = 0$		 5	 6	mA
Output Swing	Positive Negative	$V^+ - 7$ $V^- + 7$	$V^+ - 5$ $V^- + 5$		V V
Drive Current	Source (Pin 8) Sink (Pin 5)	5 5			mA mA
Noise (20 Hz–20 kHz)	Input Referred		3		μV
Supply Rejection	Input Referred	70	90		dB
Total Harmonic Distortion	f = 1 kHz f = 20 kHz		0.01 0.10	 0.25	% %
Intermodulation Distortion	60 Hz, 7 kHz, 4:1		0.01		%
Open Loop Gain	f = 1 kHz	1000	5500		V/V
Input Bias Current			0.1	1.0	μA
Input Offset Voltage			5	20	mV
Positive Current Limit V_{BE}	Pin 10–9		650		mV
Negative Current Limit V_{BE}	Pin 9–13		650		mV
Positive Current Limit Bias Current	Pin 10		10	100	μA
Negative Current Limit Bias Current	Pin 13		10	100	μA

Pin 14 Current Comments

Minimum pin 14 current required for shutdown is 0.5 mA, and must not exceed 1 mA.
Maximum pin 14 current for amplifier not shut down is 0.05 mA.
The typical shutdown switch point current is 0.2 mA.

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 90°C/W junction to ambient.

Typical Applications

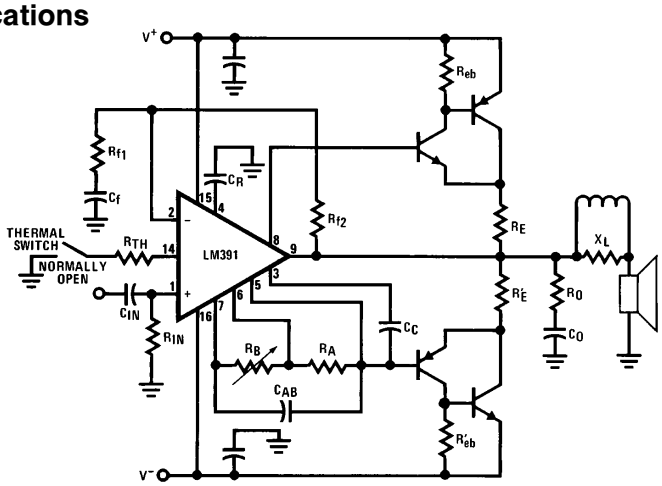

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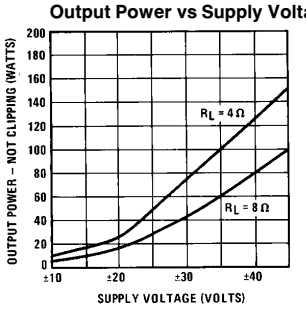
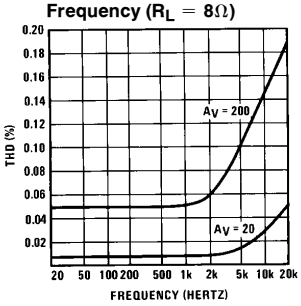
FIGURE 1. LM391 with External Components—Protection Circuitry Not Shown

Typical Performance Characteristics

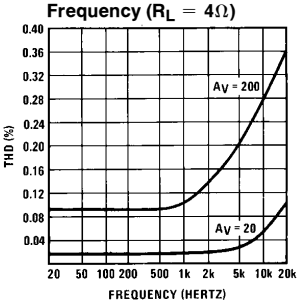
Output Power vs Supply Voltage



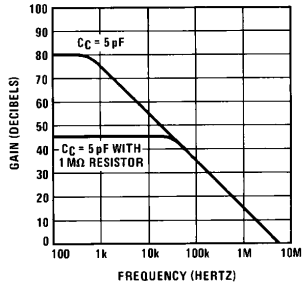
Total Harmonic Distortion vs Frequency (R_L = 8Ω)



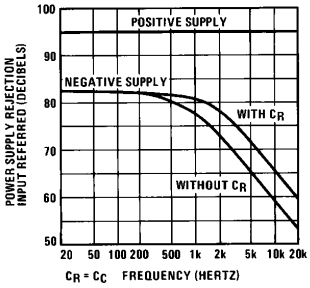
Total Harmonic Distortion vs Frequency (R_L = 4Ω)



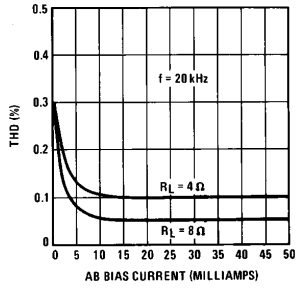
Open Loop Gain vs Frequency



Input Referred Power Supply Rejection vs Frequency



Total Harmonic Distortion vs AB Bias Current



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Pin Descriptions

Pin No.	Pin Name	Comments
1	+ Input	Audio input
2	− Input	Feedback input
3	Compensation	Sets the dominant pole
4	Ripple Filter	Improves negative supply rejection
5	Sink Output	Drives output devices and is emitter of AB bias V_{BE} multiplier
6	BIAS	Base of V_{BE} multiplier
7	BIAS	Collector of V_{BE} multiplier
8	Source Output	Drives output devices
9	Output Sense	Biases the IC and is used in protection circuits
10	+ Current Limit	Base of positive side protection circuit transistor
11	+ SOA Diode	Diode used for dual slope SOA protection
12	− SOA Diode	Diode used for dual slope SOA protection
13	− Current Limit	Base of negative side protection circuit transistor
14	Shutdown	Shuts off amplifier when current is pulled out of pin
15	V^+	Positive supply
16	V^-	Negative supply

External Components (Figure 1)

Component	Typical Value	Comments
C_{IN}	1 μF	Input coupling capacitor sets a low frequency pole with R_{IN}. $f_L = \frac{1}{2\pi R_{IN} C_{IN}}$
R_{IN}	100k	Sets input impedance and DC bias to input.
R_{f_2}	100k	Feedback resistor; for minimum offset voltage at the output this should be equal to R_{IN}.
R_{f_1}	5.1k	Feedback resistor that works with R_{f_2} to set the voltage gain. $A_V = 1 + \frac{R_{f_2}}{R_{f_1}}$
C_f	10 μF	Feedback capacitor. This reduces the gain to unity at DC for minimum offset voltage at the output. Also sets a low frequency pole with R_{f_1}. $f_L = \frac{1}{2\pi R_{f_1} C_f}$
C_C	5 pF	Compensation capacitor. Sets gain bandwidth product and a high frequency pole. $GBW = \frac{1}{2\pi 5000 C_C}$, $f_h = \frac{GBW}{A_V}$ Max f_h for stable design $\approx$ 500 kHz.
R_A	3.9k	AB bias resistor.
R_B	10k	AB bias potentiometer. Adjust to set bias current in the output stage.
C_{AB}	0.1 μF	Bypass capacitor for bias. This improves high frequency distortion and transient response.
C_R	5 pF	Ripple capacitor. This improves negative supply rejection at midband and high frequencies. C_R, if used, must equal C_C.
R_{eb}	100Ω	Bleed resistor. This removes stored charge in output transistors.
R_O	2.7Ω	Output compensation resistor. This resistor and C_O compensate the output stage. This value will vary slightly for different output devices.
C_O	0.1 μF	Output compensation capacitor. This works with R_O to form a zero that cancels f_β of the output power transistors.
R_E	0.3Ω	Emitter degeneration resistor. This resistor gives thermal stability to the output stage quiescent current. IRC PW5 type.
R_{TH}	39k	Shutdown resistor. Sets the amount of current pulled out of pin 14 during shutdown.
C_2, C'_2	1000 pF	Compensation capacitors for protection circuitry.
X_L	10$\Omega | |$5 μH	Used to isolate capacitive loads, usually 20 turns of wire wrapped around a 10Ω, 2W resistor.

Application Hints

GENERALIZED AUDIO POWER AMP DESIGN

Givens: Power Output
Load Impedance
Input Sensitivity
Input Impedance
Bandwidth

The power output and load impedance determine the power supply requirements. Output signal swing and current are found from:

$$V_{Opeak} = \sqrt{2\,R_L\,P_O} \quad (1)$$

$$I_{Opeak} = \sqrt{\frac{2\,P_O}{R_L}} \quad (2)$$

Add 5 volts to the peak output swing (V_{OP}) for transistor voltage to get the supplies, i.e., $\pm$ (V_{OP} + 5V) at a current of I_{peak}. The regulation of the supply determines the unloaded voltage, usually about 15% higher. Supply voltage will also rise 10% during high line conditions.

$$\text{max supplies} \approx \pm(V_{Opeak} + 5)\,(1 + \text{regulation})\,(1.1) \quad (3)$$

The input sensitivity and output power specs determine the required gain.

$$A_V \geq \frac{\sqrt{P_O\,R_L}}{V_{IN}} = \frac{V_{ORMS}}{V_{INRMS}} \quad (4)$$

Normally the gain is set between 20 and 200; for a 25 watt, 8 ohm amplifier this results in a sensitivity of 710 mV and 71 mV, respectively. The higher the gain, the higher the THD, as can be seen from the characteristics curves. Higher gain also results in more hum and noise at the output.

The desired input impedance is set by R_{IN}. Very high values can cause board layout problems and DC offsets at the output. The bandwidth requirements determine the size of C_f and C_C as indicated in the external component listing.

The output transistors and drivers must have a breakdown voltage greater than the voltage determined by equation (3). The current gain of the drive and output device must be high enough to supply I_{Opeak} with 5 mA of drive from the LM391. The power transistors must be able to dissipate approximately 40% of the maximum output power; the drivers must dissipate this amount divided by the current gain of the outputs. See the output transistor selection guide, Table A.

To prevent thermal runaway of the AB bias current the following equation must be valid:

$$\theta_{JA} \leq \frac{R_E\,(\beta_{MIN} + 1)}{V_{CEQMAX}\,(K)} \quad (5)$$

where:

θ_{JA} is the thermal resistance of the driver transistor, junction to ambient, in °C/W.

R_E is the emitter degeneration resistance in ohms.

β_{min} is that of the output transistor.

V_{CEQMAX} is the highest possible value of one supply from equation (3).

K is the temperature coefficient of the driver base-emitter voltage, typically 2 mV/°C.

Often the value of R_E is to be determined and equation (5) is rearranged to be:

$$R_E \geq \frac{\theta_{JA}\,(V_{CEQMAX})\,K}{\beta_{MIN} + 1} \quad (6)$$

The maximum average power dissipation in each output transistor is:

$$\overline{P_{DMAX}} = 0.4\,P_{OMAX} \quad (7)$$

The power dissipation in the driver transistor is:

$$\overline{P_{DRIVER(MAX)}} = \frac{\overline{P_{DMAX}}}{\beta_{MIN}} \quad (8)$$

Heat sink requirements are found using the following formulas:

$$\theta_{JA} \leq \frac{T_{JMAX} - T_{AMAX}}{P_D} \quad (9)$$

$$\theta_{SA} \leq \theta_{JA} - \theta_{JC} - \theta_{CS} \quad (10)$$

where:

T_{jMAX} is the maximum transistor junction temperature.

T_{AMAX} is the maximum ambient temperature.

θ_{JA} is thermal resistance junction to ambient.

θ_{SA} is thermal resistance sink to ambient.

θ_{JC} is thermal resistance junction to case.

θ_{CS} is thermal resistance case to sink, typically 1°C/W for most mountings.

Application Hints (Continued)

PROTECTION CIRCUITRY

The protection circuits of the LM391 are very flexible and should be tailored to the output transistor's safe operating area. The protection V-I characteristics, circuitry, and resistor formulas are described below. The diodes from the output to each supply prevent the output voltage from exceeding the supplies and harming the output transistors. The output will do this if the protection circuitry is activated while driving an inductive load.

TURN-ON DELAY

It is often desirable to delay the turn-ON of the power amplifier. This is easily implemented by putting a resistor in series with a capacitor from pin 14 to ground. The value of the resistor is set to limit the current to less than 1 mA (the absolute maximum). This resistor with the capacitor gives a time constant of RC. The turn-ON delay is approximately 2 time constants.

Example:

Amplifier with maximum supply of 30V, like the 20W, 8Ω example in the data sheet, requiring a delay of 1 second.

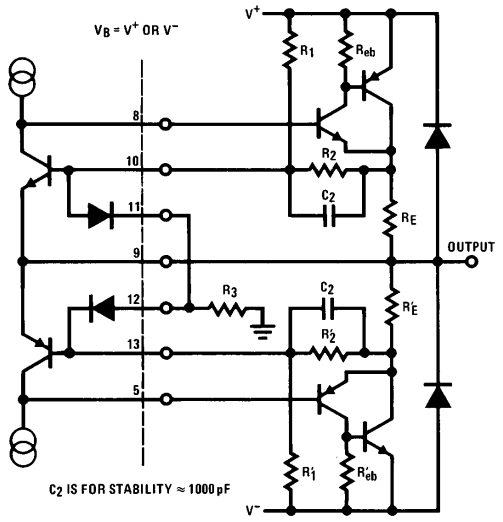
Time delay = 2 RC

$$R = \frac{\text{Max } V^+}{1\text{ mA}}$$

So:

R = 30k. Solving for C gives 16.7 μF. Use C = 20 μF with a 30V rating.

Protection Circuitry with External Components



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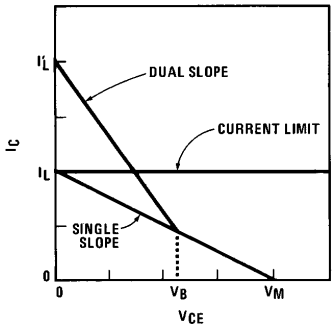
Protection Characteristics



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Protection Circuit Resistor Formulas ($V_B = V^+$)

Type of Protection	R_E, R'	R_1, R'_1	R_2, R'_2	R_3, R'_3
Current Limit	$R_E = \frac{\phi}{I_L}$	Not Required	Short	Not Required
Single Slope SOA Protection	$R_E = \frac{\phi}{I_L}$	$R_1 = R_2\left(\frac{V_M - \phi}{\phi}\right)$	1 kΩ	Not Required
Dual Slope SOA Protection ($V_B = V^+$)	$R_E = \frac{\phi}{I_L}$	$R_1 = R_2\left(\frac{V_M - \phi}{\phi}\right)$	1 kΩ	$R_3 = R_2\left[\frac{V^+}{I'_L R_E - \phi} - 1\right]$

Note: ϕ is the current limit V_{BE} voltage, 650 mV. Assumptions: $V^+ >> \phi$, $V_M >> \phi$. V^+ is the load supply voltage. V_M is the maximum rated V_{CE} of the output transistors.

Application Hints (Continued)

TRANSIENT INTERMODULATION DISTORTION

There has been a lot of interest in recent years about transient intermodulation distortion. Matti Otala of University of Oulu, Oulu, Finland has published several papers on the subject. The results of these investigations show that the open loop pole of the power amplifier should be above 20 kHz.

To do this with the LM391 is easy. Put a 1 MΩ resistor from pin 3 to the output and the open loop gain is reduced to about 46 dB. Now the open loop pole is at 30 kHz. The current in this resistor causes an offset in the input stage that can be cancelled with a resistor from pin 4 to ground. The resistor from pin 4 to ground should be 910 kΩ rather than 1 MΩ to insure that the shutdown circuitry will operate correctly. The slight difference in resistors results in about 15 mV of offset. The 40W, 8Ω amplifier schematic shows the hookup of these two resistors.

BRIDGE AMPLIFIER

A switch can be added to convert a stereo amplifer to a single bridge amplifer. The diagram below shows where the switch and one resistor are added. When operating in the bridge mode the output load is connected between the two outputs, the input is V_{IN} #1, and V_{IN} #2 is disconnected.

OSCILLATIONS & GROUNDING

Most power amplifiers work the first time they are turned on. They also tend to oscillate and have excess THD. Most oscillation problems are due to inadequate supply bypassing and/or ground loops. A 10 μF, 50V electrolytic on each power supply will stop supply-related oscillations. However, if the signal ground is used for these bypass caps the THD is usually excessive. The signal ground must return to the power supply alone, as must the output load ground. All other grounds—bypass, output R-C, protection, etc., can tie together and then return to supply. This ground is called high frequency ground. On the 40W amplifier schematic all the grounds are labeled.

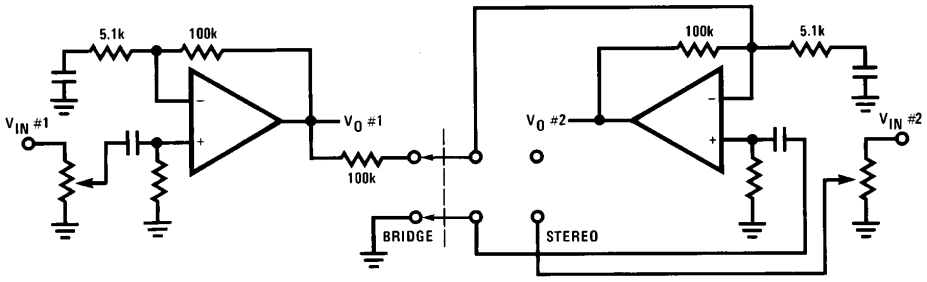
Capacitive loads can cause instabilities, so they are isolated from the amplifier with an inductor and resistor in the output lead.

AB BIAS CURRENT

To reduce distortion in the output stage, all the transistors are biased ON slightly. This results in class AB operation and reduces the crossover (notch) distortion of the class B stage to a low level, (see performance curve, THD vs AB bias). The potentiometer, R_B, from pins 6–7 is adjusted to give about 25 mA of current in the output stage. This current is usually monitored at the supply or by measuring the voltage across R_E.

Typical Applications (Continued)

Bridge Circuit Diagram



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Output Transistors Selection Guide

Table A.

Power Output	Driver Transistor		Output Transistor	
	PNP	NPN	PNP	NPN
20W @ 8Ω 30W @ 4Ω	MJE711 MJE171 D43C8	MJE721 MJE181 D42C8	TIP42A 2N6490	TIP41A 2N6487
40W @ 8Ω 60W @ 4Ω	MJE712 MJE172 D43C11	MJE722 MJE182 D42C11	2N5882	2N5880

Application Hints (Continued)

A 20W, 8Ω; 30W, 4Ω AMPLIFIER

Givens:

Power Output	20W into 8Ω 30W into 4Ω
Input Sensitivity	1V Max
Input Impedance	100k
Bandwidth	20 Hz–20 kHz ± 0.25 dB

Equations (1) and (2) give:

20W/8Ω $V_{OP} = 17.9V$ $I_{OP} = 2.24A$

30W/4Ω $V_{OP} = 15.5V$ $I_{OP} = 3.87A$

Therefore the supply required is:

±23V @ 2.24A, reducing to . . .

±21V @ 3.87A

With 15% regulation and high line we get ±29V from equation (3).

Sensitivity and equation (4) set minimum gain:

$$A_V \geq \frac{\sqrt{20 \times 8}}{1} = 12.65$$

We will use a gain of 20 with resulting sensitivity of 632 mV.

Letting R_{IN} equal 100k gives the required input impedance. For low DC offsets at the output we let $R_{f_2} = 100k$. Solving for R_{f_1} gives:

$$R_{f_2} = 100k$$

$$R_{f_1} = \frac{100k}{20 - 1} = 5.26k; \text{ use } 5.1k$$

The bandwidth requirement must be stated as a pole, i.e., the 3 dB frequency. Five times away from a pole gives 0.17 dB down, which is better than the required 0.25 dB. Therefore:

$$f_L = \frac{20}{5} = 4 \text{ Hz}$$

$$f_h = 20k \times 5 = 100 \text{ kHz}$$

Solving for C_f:

$$C_f \geq \frac{1}{2\pi R_{f_1} f_L} = 7.8\ \mu F; \text{ use } 10\ \mu F$$

The recommended value for C_C is 5 pF for gains of 20 or larger. This gives a gain-bandwidth product of 6.4 MHz and a resulting bandwidth of 320 kHz, better than required.

The breakdown voltage requirement is set by the maximum supply; we need a minimum of 58V and will use 60V. We must now select a 60V power transistor with reasonable beta at I_{Opeak}, 3.87A. The TIP42, TIP41 complementary pair are 60V, 60W transistors with a minimum beta of 30 at 4A. The driver transistor must supply the base drive given 5 mA drive from the LM391. The MJE711, MJE721 complementary driver transistors are 60V devices with a minimum beta of 40 at 200 mA. The driver transistors should be much faster (higher f_T) than the output transistors to insure that the R-C on the output will prevent instability.

To find the heat sink required for each output transistor we use equations (7), (9), and (10):

$$\overline{P_D} = 0.4\ (30) = 12W \quad (7)$$

$$\theta_{JA} \leq \frac{150°C - 55°C}{12} = 7.9°C/W \text{ for } T_{AMAX} = 55°C \quad (9)$$

$$\theta_{SA} \leq 7.9 - 2.1 - 1.0 = 4.8°C/W \quad (10)$$

If both transistors are mounted on one heat sink the thermal resistance should be halved to 2.4°C/W.

The maximum average power dissipation in each driver is found using equation (8):

$$\overline{P_{DRIVER(MAX)}} = \frac{12}{30} = 400 \text{ mW}$$

Using equation (9):

$$\theta_{JA} \leq \frac{155 - 55}{0.4} = 237°C/W$$

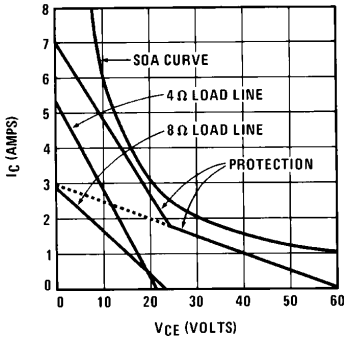
Application Hints (Continued)

Since the free air thermal resistance of the MJE711, MJE721 is 100°C/W, no heat sink is required. Using this information and equation (6) we can find the minimum value of R_E required to prevent thermal runaway.

$$R_E \geq \frac{100\ (30)\ (0.002)}{30 + 1} = 0.19\Omega \qquad (6)$$

We must now use the SOA data on the TIP42, TIP41 transistors to set up the protection circuit. Below is the SOA curve with the 4Ω and 8Ω load lines. Also shown are the desired protection lines. Note the value of V_B is equal to the supply voltage, so we use the formulas in the table.

D.C. SOA of TIP42, TIP41 Transistors



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The data points from the curve are:

$$V_M = 60V,\ V_B = 23V,\ I_L = 3A,\ I_L' = 7A$$

Using the dual slope protection formulas:

$$R_E = \frac{0.65}{3} = 0.22\Omega$$

$$R_2 = 1k$$

$$R_1 = 1k\left(\frac{60 - 0.65}{0.65}\right) \approx 91k$$

$$R_3 = 1k\left(\frac{23}{7(0.22) - 0.65} - 1\right) \approx 24k$$

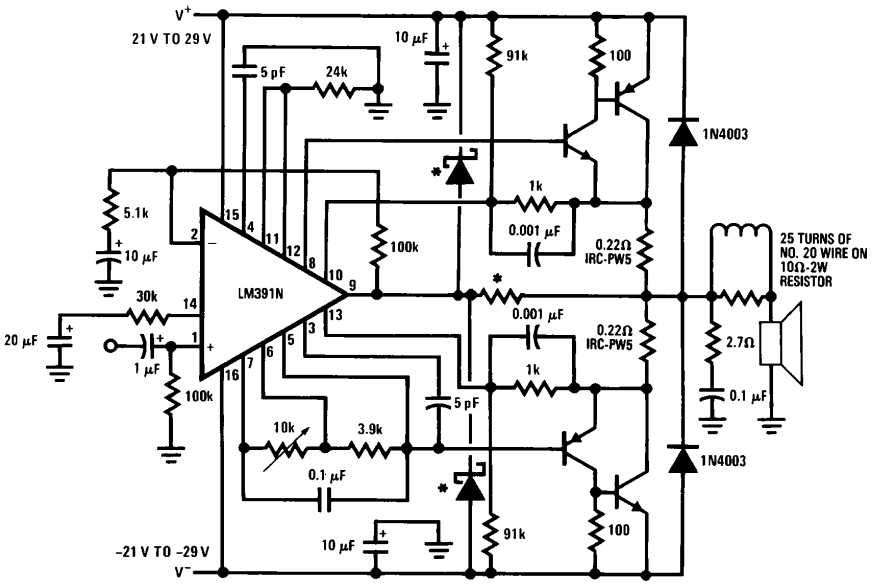
Note that an R_E of 0.22Ω satisfies equation (6). The final schematic of this amplifier is below. If the output is shorted the current will be 1.8A and V_{CE} is 23V. Since the input is AC, the average power is:

$$\text{short } \overline{P_D} = \tfrac{1}{2}(1.8)\ (23) \approx 21W$$

This power is greater than was used in the heat sink calculations, so the transistors will overheat for long-duration shorts unless a larger heat sink is used.

Typical Applications (Continued)

20W-8Ω, 30W-4Ω Amplifier with 1 Second Turn-ON Delay



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*Additional protection for LM391N; Schottky diodes and R ≈ 100Ω.

Application Hints (Continued)

A 40W/8Ω, 60W/4Ω AMPLIFIER

Given:

Power Output	40W/8Ω 60W/4Ω
Input Sensitivity	1V Max
Input Impedance	100k
Bandwidth	20 Hz–20 kHz ± 0.25 dB

Equations (1) and (2) give:

40W/8Ω $V_{OPeak} = 25.3V$ $I_{OPeak} = 3.16A$

60W/4Ω $V_{OPeak} = 21.9V$ $I_{OPeak} = 5.48A$

Therefore the supply required is:

±30.3V @ 3.16A, reducing to . . .

±26.9V @ 5.48A

With 15% regulation and high line we get ±38.3V using equation (3).

The minimum gain from equation (4) is:

$$A_V \geq 18$$

We select a gain of 20; resulting sensitivity is 900 mV.

The input impedance and bandwidth are the same as the 20 watt amplifier so the components are the same.

$R_{f_1} = 5.1k$ $R_{IN} = 100k$ $C_C = 5\ pF$

$R_{f_2} = 100k$ $C_f = 10\ \mu F$

The maximum supplies dictate using 80V devices. The 2N5882, 2N5880 pair are 80V, 160W transistors with a minimum beta of 40 at 2A and 20 at 6A. This corresponds to a minimum beta of 22.5 at 5.5A (I_{Opeak}). The MJE712, MJE722 driver pair are 80V transistors with a minimum beta of 50 at 250 mA. This output combination guarantees I_{Opeak} with 5 mA from the LM391.

Output transistor heat sink requirements are found using equations (7), (9), and (10):

$$\overline{P_D} = 0.4\,(60) = 24W \quad (7)$$

$$\theta_{JA} \leq \frac{200 - 55}{24} = 6.0°C/W \text{ for } T_{AMAX} = 55°C \quad (9)$$

$$\theta_{SA} \leq 6.0 - 1.1 - 1.0 = 3.9°C/W \quad (10)$$

For both output transistors on one heat sink the thermal resistance should be 1.9°C/W.

Now using equation (8) we find the power dissipation in the driver:

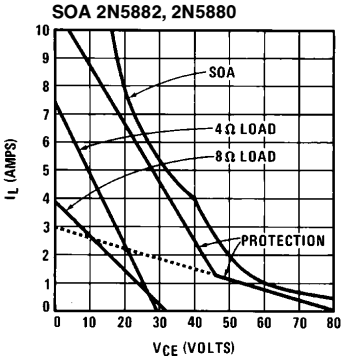
$$\overline{P_{DRIVER}} = \frac{24}{20} = 1.2W \quad (8)$$

$$\theta_{JA} \leq \frac{150 - 55}{1.2} = 79°C/W \quad (9)$$

Since a heat sink is required on the driver, we should investigate the output stage thermal stability at the same time to optimize the design. If we find a value of R_E that is good for the protection circuitry, we can then use equation (5) to find the heat sink required for the drivers.

The SOA characteristics of the 2N5882, 2N5880 transistors are shown in the following curve along with a desired protection line.

SOA 2N5882, 2N5880



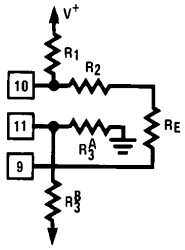
TL/H/7146–10

The desired data points are:

$V_M = 80V$ $V_B = 47V$ $I_L = 3A$ $I_L' = 11A$

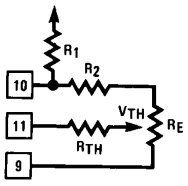
Since the break voltage is not equal to the supply, we will use two resistors to replace R_3 and move V_B.

Circuit Used



TL/H/7146–11

Thevenin Equivalent



Where: $R_{TH} = R_3^A \parallel R_3^B$

$$V_{TH} = V^- \left[\frac{R_3^A}{R_3^A + R_3^B}\right]$$

TL/H/7146–12

Application Hints (Continued)

The formulas for R_E, R_1, and R_2 do not change:

$$R_E = \frac{0.65}{3A} = 0.22\Omega$$

$$R_2 = 1k \qquad R_1 = 1k\frac{80 - 0.65}{0.65} = 120k$$

The formula for R_3 now gives R_{TH} when the V^+ in the formula becomes V_B.

$$R_{TH} = R_2\left[\frac{V_B}{I_L R_E - \phi} - 1\right]$$

$$= 1k\left[\frac{47}{11\,(0.22) - 0.65} - 1\right] = 25.55k$$

V_{TH} is the additional voltage added to the supply voltage to get V_B.

$$V_{TH} = -(V_B - V^+) = -(47 - 30) = -17V$$

Now we must find R_3^A and R_3^B using the Thevenin formulas. Putting V_{TH}, V^-, and R_{TH} into the appropriate formulas reduces to:

$$R_3^B = 0.76\,R_3^A \qquad \text{and} \qquad 25.55k = R_3^A \,||\, R_3^B$$

The easiest way to solve these equations is to iterate with standard values. If we guess $R_3^A = 62k$, then $R_3^B = 47.12k$; use 47k. The Thevenin impedance comes out 26.7k, which is close enough to 25.55k.

Now we will use equation (5) to determine the heat sinking requirements of the drivers to insure thermal stability:

$$\theta_{JA} \le \frac{0.22\,(20 + 1)}{40\,(0.002)} \approx 57°C/W \qquad (5)$$

This value is lower than we got with equation (9), so we will use it in equation (10):

$$\theta_{SA} \le 57 - 6 - 1 = 50°C/W \qquad (10)$$

This is the required heat sink for each driver. For low TIM we add the 1 MΩ resistor from pin 3 to the output and a 910k resistor from pin 4 to ground. The complete schematic is shown below.

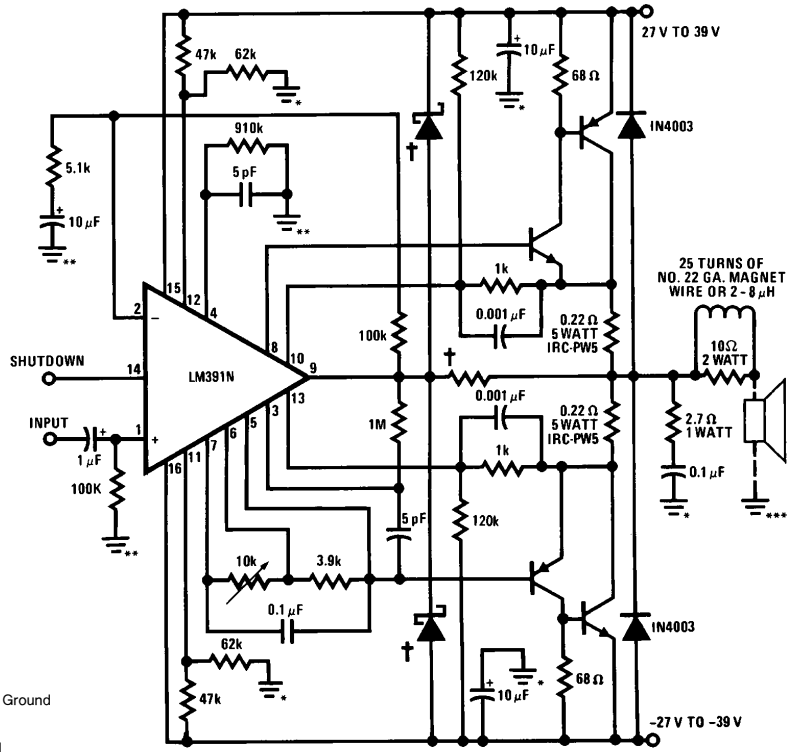
If the output is shorted, the transistor voltage is about 28V and the current is 5A. Therefore the average power is:

$$\text{short } \overline{PD} = \tfrac{1}{2}(28)\,5 = 70W$$

This is much larger than the power used to calculate the heat sinks and the output transistors will overheat if the output is shorted too long.

Typical Applications (Continued)

40W-8Ω, 60W-4Ω Amplifier



*High Frequency Ground

**Input Ground

***Speaker Ground

Note: All Grounds Should be Tied Together Only at Power Supply Ground.

†Additional protection for LM391N; Schottky diodes and R ≅ 100Ω.

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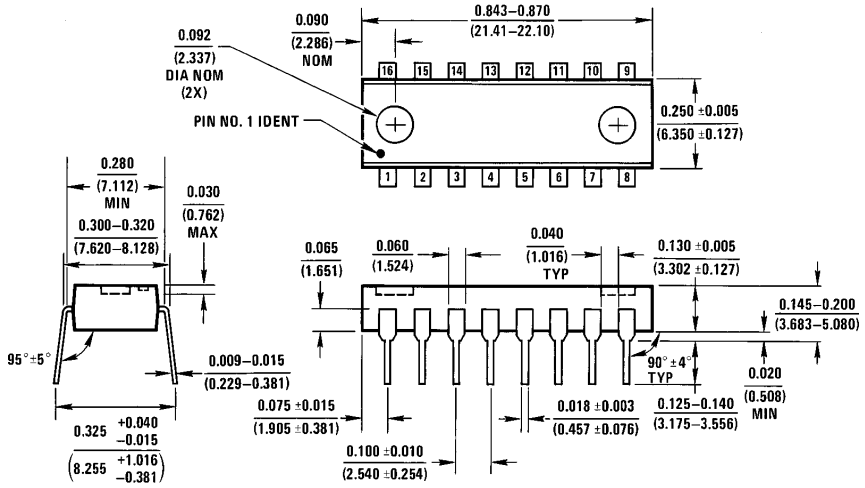
Physical Dimensions inches (millimeters)



N16A (REV E)

Molded Dual-In-Line Package (N)
Order Number LM391N-100
NS Package Number N16A

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